Ocean Observations

Online textbook at

http://www-pord.ucsd.edu/~Italley/sio210/pickard_emery/chapter_6.pdf

A story told by Senya Grodsky/UMCP

Retrospective story **"From wooden bucket to modern satellite** sensors"







Why we care about data taken by obsolete methods?

All data are to be used in order to construct the longest possible records of the ocean climate.

In-situ observations

Remote Sensing



High precision Vertical resolution All ocean variables Limited coverage Retrieve variables from E/M fields N/A Only surface variables Global coverage

In situ observations

 Temperature and salinity
 Velocity



Blake



Steel wire cable for dredging and anchoring. (from Blake, NOAA Photo Library) http://oceanexplorer.noaa.gov/history/breakthru/media/13_steeldredge.html

Early days of observational oceanography





Early days tools for measuring SST

(a) Traditional wooden bucket used to collect surface samples.(b) Special bucket samplers for sea surface temperature measurements.On the right is a canvas bucket and the two on the left are metal containers (Folland et al, 2000).

Temperature of water samples on board can differ from in-situ temperature, due to sun heating, evaporation, etc.

 \rightarrow In-situ temperature measurements

Early da The reversing thermometer measurements need performing a buoy station to deploy the chain that is time consuming.

Thermometer depth is calculated given the rope deviation from the vertical. This is subject to errors at strong drift and in the presence of vertically sheared currents.

Vertical sampling is limited because the weight needs space to accelerate.

Failure of a reversing sensor at any horizon makes all sensors at deeper horizons unreleased.

Oceanographers start developing temperature profiling instruments.

Nansen water bottles before (I), during (II), and after (III) reversing. (From Dietrich et al. 1980)

Water sampling bottles (Nansen Bottles) for mounting individually on a wire with reversing thermometer racks.

Temperature measurements

- MBT
- XBT
- CTD
- PALACE floats (evolving into ARGO)
 Moored buoys

Number of grid points on a 2x2 deg grid filled with data. Data verage **MBT-** Mechanical Bathythermograph mes from XBT- Expandable Bathythermograph CTD- Conductivity, Temperature, Depth — MBT — XBI OSD- Ocean Station Data (Bravo in the Labrador Sea, Bermuda, Hawaii, etc) PFL- Profiling Floats (RAFOS evolving in ARGO) PFI - DRB **DRB-** Drifting Buoys MRE MRB- Moored Buoys (TAO-Pacific, PIRATA-Atlantic) Nu 1970 1990 1960 985 980

Number of points on a 2° x 2° x month grid filled with data.









Mechanical bathythermograph (MBT), in use from 1951 to 1975. It is obsolete now and is replaced by **expandable** bathythermograph (XBT)

MBT temperature profile

XBT (Expendable Bathythermograph)

•May be deployed underway. Deployment may be automatic
•Thermistor error: ~0.1C
•Limited generally 400m (T4) – 750m (T7)
•Droprate error: ~1%
•RMSnoise/RMSsignal: 8%
•Total: 5x10⁶ since the 1960's



Air-dropped: AXBT (pictures from Sippican)



XBT by Lockheed Martin Sippican, Inc





As an XBT drops down, the cooper wire is released from the instrument body. The wire electrical resistance changes as a function of the depth integrated temperature. XBT is an easy to launch instrument. It is widely used from voluntary observing ships. But instrument depth is not measured and is calculated based on the drop rate relationship \leftarrow Potential source of bias.



XBT autolauncher developed for multiple probes by Scripps Institution of Oceanography (courtesy G. Pezzoli and D. Roemmich).

Warming of the Global Ocean. Bias of the XBT instrumentation.



Time series of layer-averaged monthly potential temperature anomalies and the area fraction of the global ocean observed at each level. Data are separated by instrument type and by combining all instruments. Missing data are denoted by gray areas. (K. M. AchutaRao et al., 2007)

Global Data Coverage, 2x2 deg x 1month grid



CTD (<u>Conductivity</u>, <u>Temperature</u>, <u>Depth probe</u>)



Requires motionless platform, winch
May carry rosette for nutrients, etc.
Full depth
Measures salinity, possibly O2
Temperature error: 0.015C
RMSnoise/RMSsignal: 2%



The Neil Brown CTD is lowered through the water on the end of an electrical conductor cable that transmits the information to computers or recorders on board ship.

The Seabird CTD eliminates the complex infrastructure of having a conducting wire to transfer the signal from the CTD to the ship. It records internally and can be used with a simple support cable or on a mooring. Upon return to the surface this CTD is plugged into a computer and the data are downloaded for processing and display.

Neil-Brown Mark IV CTD

Seabird CTD

Station time series (Bermuda and Hawaii)

- http://hahana.soest.hawaii.edu/ hot/
- http://www.bbsr.edu/



http://www.bbsr.edu/users/ctd/mot ero/HSsst.html



Bermuda surface mooring http://www.opl.ucsb.edu/btm_text/buoy_photos.html

TAO /PIRATA tropical moorings





http://www.pmel.noaa.gov/tao/proj _over/proj_over.html



http://www.pmel.noaa.gov/tao

http://www.brest.ird.fr/pirata/reseauus.html



TAO buoys being serviced.



(b) Layout of TAO mooring.(From the TAO website at NOAA/PMEL: http://www.pmel.noaa.gov/tao)



Time series of wind, dynamic height and temperature in the vertical at 0N, 110W

Monthly SST 2°S to 2°N Average



Time – longitude diagram of surface temperature along the equator in the Pacific. Note up to 5 degC warm anomaly in the eastern equatorial sector during the 1997-98 record El Nino.

Monthly SST at the Equator



Time – longitude diagram of surface temperature along the equator in the Atlantic. Note up to 2 degC warm anomalies in the eastern equatorial sector that are referenced as the Atlantic Ninos (after the Pacific El Nino).

Standard ocean measurements are taken on board of research (or voluntary observing) vessels or from ocean moorings.

Ship time is costly. Buoy servicing also requires ship time. Oceanographers launch development of profiling floats.



Simple Mission Operation: The float descends to cruising depth, drifts for several days, ascends while taking salinity and temperature profiles, and then transmits data to satellites. All the mission parameters, such as the drift depth, vertical sampling resolution, and time on the surface, can be tailored to suit the operating region.

Argo deployment Research Vessels









Pay off.

Satellite

Argo float is like an autonomous CTD profiler.

Conductivity sensor of a CTD needs periodic calibrations.

As Argo float is launched and operates during a few years the conductivity sensor drifts that affects salinity data. This problem is still to be solved.

profiler that, its buoyancy

~110cm

This drift is of the order of 0.1 psu during a lifetime. It is negligible comparing to spatial Hydraulic pu variation of salinity over the Global Ocean. that changes But the drift creates substantial problems for putting the ARGO data into climate time series.



The operational analysis system set up by the CORIOLIS data center in France produces temperature and salinity gridded fields by using profiles from the data base.

These profiles are for more than 80% acquired within the Argo program. The system is based on an statistical estimation method (objective analysis).



CORIOLIS 10m-depth salinity analysis. Data are available at http://www.coriolis.eu.org/cdc/ObjectivesAnalysis/objective_analyses.htm

Mixed layer depth from ARGO



2.10 (see p. 135) Mixed-layer depths in the Labrador Sea reported in real time by P-ALACE floats between er 1996 and April 1997. From Lavender *et al.* (2000b).

Velocity measurements

- Drogued surface drifters
- ADCPs
- Propeller-type current meters
- CODAR



Surface drifter construction





The WOCE/TOGA Lagrangian Drifter



Diagram displaying the low-cost Global Lagrangian Drifter on the left hand side, and schematics of the sensor attachments (barometer, submergence, SST, irradiance and SEACAT), on the right hand side. Host drifters are also equipped with drogue sensors that indicate drogue loss. Buoys without drogues do not depict ocean currents accurately, because the drifter becomes susceptible to wave and wind action. Drifters transmit sensor data to satellites that determine the buoy's position and relay the data to Argos ground stations. Service Argos provides raw drifter data to the DAC where the data is processed and distributed.






1979-2006 mean Atlantic circulation (streamfunction)



Surface drifter currents

Acoustic Doppler Current Profilers

- Depth range varies with frequency
 - 600 kHz 70-85m
 - 300 kHz 240-300m
- Shipboard data archived Joint Archive for Shipboard ADCP
 - http://ilikai.soest.hawaii.edu/sadcp





http://www.rdinstruments.com/hadcp.html

Ship section across the equator: http://moli.soest.hawaii.edu/kaimi/ka

9701L1/sectE.gif

Data collected aboard NOAA Ship Ka'imimoana and processed at the University of Hawaii.

Zonal currents from ADCP installed on the PIRATA mooring in the equatorial Atlantic at 0N, 23W





Vector Measuring Current Meter (VMCM)

Batteries \rightarrow

Sea Tech Transmissometer \rightarrow

http://woodshole.er.usgs.gov/staffpages/mmartini/instment/vmbosto n.htm

CODAR

http://www.codaros.com/seasonde.htm

- Bragg scattering of RADAR pulse
- 50 Watt transmitter at 13 Mhz
- Range: 40 70km, 1km res



Remote sensing of the oceans

- Orbits
- Electromagnetic spectrum
 - Atmospheric absorption, properties of the ocean
- Passive vs Active instruments
 Lots of examples



Orbits Low Earth Orbit (400-1500 km): often sun-synchronous orbit High Earth Orbit (36000 km):

- Geosynchronous orbit



Near polar orbit



Footprints of GOES and Meteosat

Figure 3.3 Example of geostationary satellite coverage

Passive sensors

Detect the Sun radiation reflected by the Earth of the Earth thermal radiation

SST Ocean color

Active Sensors

Send electromagnetic pulse and detect the backscattered radiation. **Ocean winds** Sea level Precipitation Surface Waves

Surface heat flux



http://rseol.gsfc.nasa.gov



Scatterometry, Satellite ocean winds



Scatterometer measures the normalized radar cross-section of the ocean surface (by comparing the power of transmitted and returned signals) from which the near-surface wind is estimated. Radar crosssection is a function of the ocean surface roughness which is created primarily by wind-generated waves. Thus wind speed and direction can be inferred.



Bragg scattering: A plan-parallel radar beam with wavelength λ hits the rough ocean surface at incidence angle θ , where capillary gravity waves with Bragg wavelength $\lambda_{\rm B}$ will cause microwave resonance.

Scatterometer wind direction retrieval



Discrete angular beams



Conical angular scanning. SeaWinds viewing geometry. Image courtesy of <u>Spencer, Wu, and Long</u> (2000). Mean winds are significant in the trade wind areas and south of 40S.

701

601

Transient wind forcing dominates the middle latitudes of the Northern Hemisphere

¹⁰^h North-easterly trades
 ^{EC} don't occur in the
 ¹⁰⁵ Indian Ocean.
 ²⁰⁵

Winds are upwelling favorable along the western coast of Africa and Americas.

 ⁷⁰⁵ ITCZ is present in the Pacific and Atlantic but not in the Indian.

SPCZ is permanent feature in the Pacific. SACZ doesn't show up in mean winds.

er winds [m/s] averaged 1999-2006



Standard Deviation of seasonaly averaged winds [m/s]





Standard deviation of winds from the seasonal cycle [m/s]









GrADS: COLA/IGES



GrADS: COLA/IGES

Satellite altimetry



http://www.aviso.oceanobs.com

Satellite altimetry allows to measure the Sea Surface Height (SSH) with a few centimeters precision.

Unfortunately, the satellite orbit is referenced to the earth ellipsoid, and the sea surface elevation measured is also reference to the ellipsoid. This elevation contains the marine geoid plus the sea elevation due to the oceanic circulation (ie the dynamic topography).

The marine geoid is poorly known (precision of a meter...) but is stationary (not changing over the time). In that way, what we do is to remove the Mean Sea Height (after several altimetric measurements over the same point of the ocean, a mean temporal value can be calculated, and this mean sea height would contains the marine geoid plus the permanent height of the dynamic topography). Then we obtain Sea Level Anomalies.

So we can study the VARIABLE PART of the ocean circulation!

Mean Dynamic Topography (AVISO) [cm]



Sea Level STD [cm], 1992-2006









Seasonal variation of sea level. The water warms in Summer, and cools in Winter, thus explaining a difference of about + or - 10 cm in the sea level between the seasons, with the seasons being inversed in the Northern and Southern Hemisphere.

Moreover, ocean stays warm or cold for some time, with a roughly two months delay with the calendar seasons, thus explaining the highs or lows in Fall or Spring. The amplitude of the variations in sea level due to the seasons shows the quantity of heat kept in stock in the ocean, and thus its impact on the climate.

Time Averaged SST [degC], 1982-2006



Satellite SST datasets

 Objectively analyzed AVHRR (Infra Red) plus in situ SST (Reynolds and Smith), 1982-present

http://www.emc.ncep.noaa.gov/research/cmb /sst_analysis/

 Microwave SST from the Tropical Rainfall measuring Mission Temperature Microwave Imager (TMI), 1998-present

http://www.ssmi.com

SST

• Infrared (near 3.7 μm for night, near 10 μm for day)

- Advanced Very High Resolution Radiometer (AVHRR)
- Along-Track Scanning Radiometer (ATSR [ERS series])
- Geostationary Operational Environmental Satellite (GOES) Imager
- Moderate Resolution Imaging Spectro-radiometer (MODIS)
- Microwave (7-10 GHz)
 - Scanning Multichannel Microwave Radiometer (SMMR)
 - TRMM Microwave Imager (TMI)
 - Advanced Microwave Scanning Radiometer (AMSR)

John Maurer, UC Boulder http://cires.colorado.edu/~maurerj/class/SST_presentation.htm

Infrared vs microwave SST

Better coverage vs better spatial resolution & accuracy

More cloud contamination -

infrared



AVHRR SST February 1 5, 2000

TMI SST February 1-5, 2000



John Maurer, UC Boulder http://cires.colorado.edu/~maurerj/class/SST_presentation.htm

microwave



Larger uncertainty

OA SST, Standard Deviation [degC], 1982-2006









(Figure Courtesy of Dr. Michael Behrenfeld)

http://disc.gsfc.nasa.gov/oceancolor/



Ocean color channels

Atm and ocn-leaving radiance

Atmospheric radiance: 90% scattering

•SeaWiFS (1997-): 8 spectral bands

1/412 nm (violet): Gelbstoffe

2/443 (blue): Chlorophyll

3/ 490 (blue-green): Pigment absorption (Case 2), K(490)

4/510 (blue-green): Chlorophyll

5/555 (green): Pigments, sediments

6/ 670 (red): Atmospheric correction

7/ 765 (near IR): Atmospheric correction, aerosol radiance

8/ 865 (near IR): Atmospheric correction, aerosol radiance

•MODIS

(on Aqua 1999- and Terra 2001-): 36 spectral bands



Relationship between passive radiance and pigment concentration



Gordon et al. (1988)








Catch the Wave: Equatorial Pacific Waves This eleven-day SeaWiFS chlorophyll-a composite January 8-18, 2002 shows the rather remarkable development of a series of <u>equatorial Pacific tropical</u> <u>instability waves</u>. The enhanced chlorophyll concentrations associated with the waves extend from the region just west of the Galapagos Islands along the equator to the dateline - a distance of nearly 10,000 kilometers.

Chlorophyll Concentration (mg / m3) MODIS (Aqua) 15 November 2004 Sea Surface Temperature (°C) MODIS (Aqua) 15 November 200

Wind blowing across the Gulf of Tehuantepec causes upwelling of cold, nutrientrich water which fuels phytoplankton blooms.

Quickscat Winds (m/s) 15 November 2004





Where we hope to see the biggest advances in the ocean observing system? **Remote sensing** Ocean salinity from space (AQUARIUS mission) In-situ Progress of the ARGO float Program