



*JCSDA Summer Colloquium on Data Assimilation
Stevenson, Washington*

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Land data assimilation

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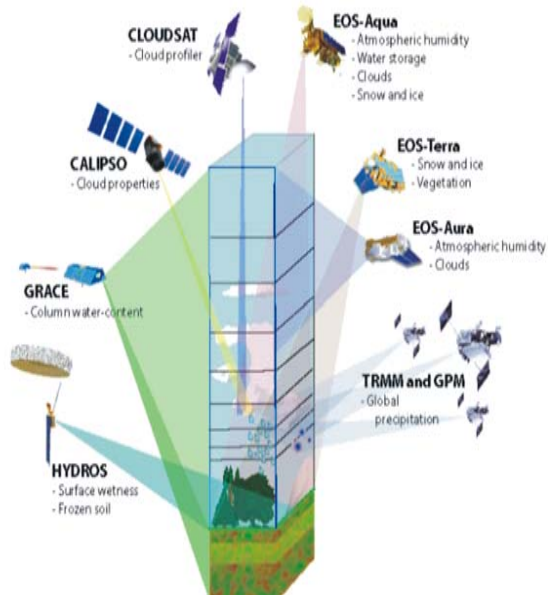
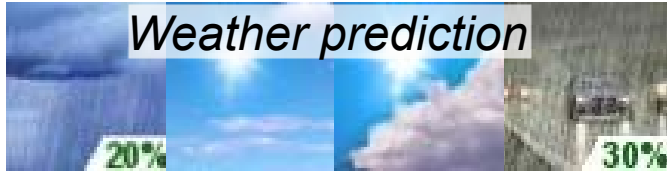
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301-614-5693

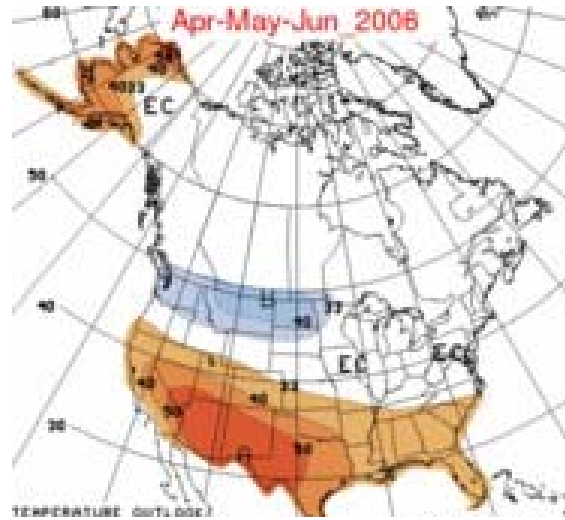


Motivation

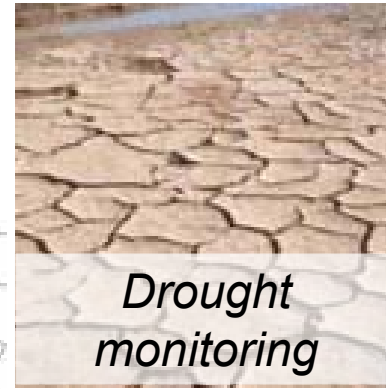
Weather prediction



Remote sensing



Seasonal climate prediction



Drought monitoring



Water resources



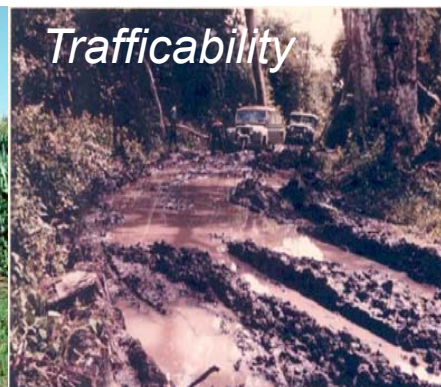
Runoff to ocean



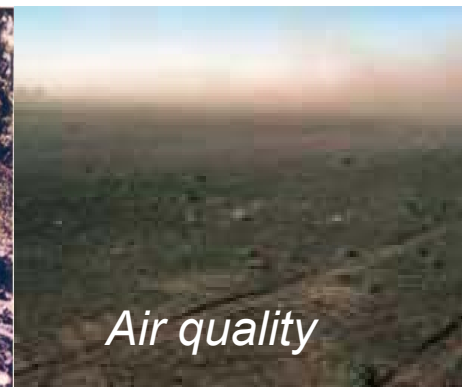
Flood forecasts



Agriculture



Trafficability



Air quality



Outline

Land surface observations and modeling

Land data assimilation methods

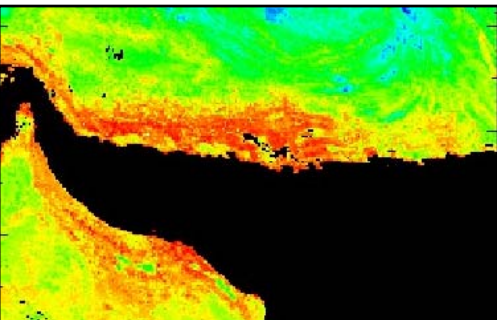
Examples – NOT a review!

- Soil moisture
- Land surface temperature
- Snow
- Terrestrial water storage

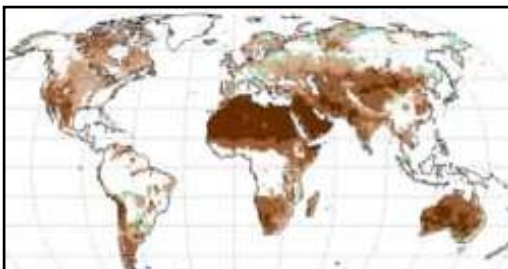
Error modeling and adaptive filtering



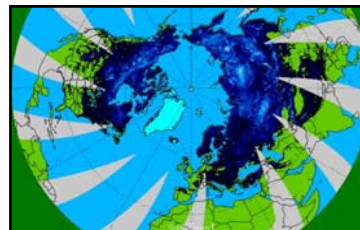
Satellite observations



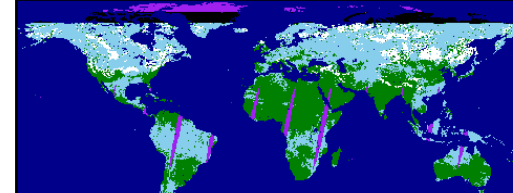
Land surface temperature (MODIS, AVHRR, GOES, ...)



Surface soil moisture (SMMR, TRMM, AMSR-E, SMOS, Aquarius, SMAP)



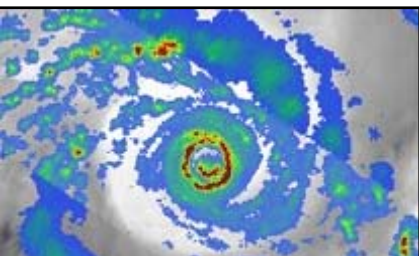
Snow water equivalent (AMSR-E, SSM/I, SCLP)



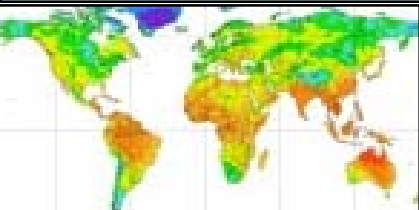
Snow cover fraction (MODIS, VIIRS, MIS)



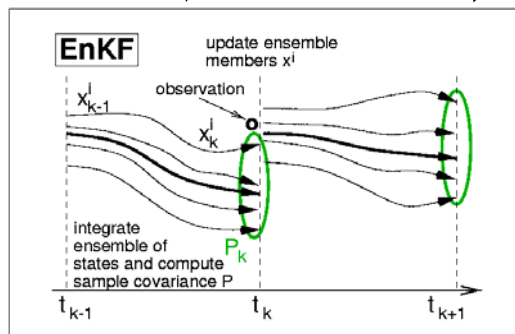
Water surface elevation (SWOT)



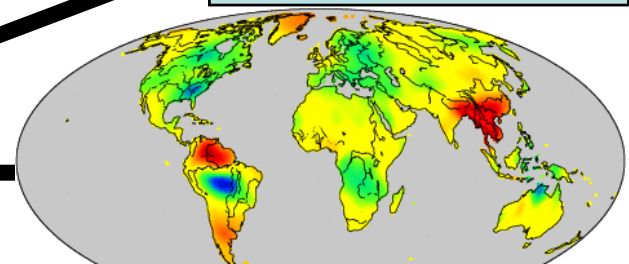
Precipitation (TRMM, GPM)



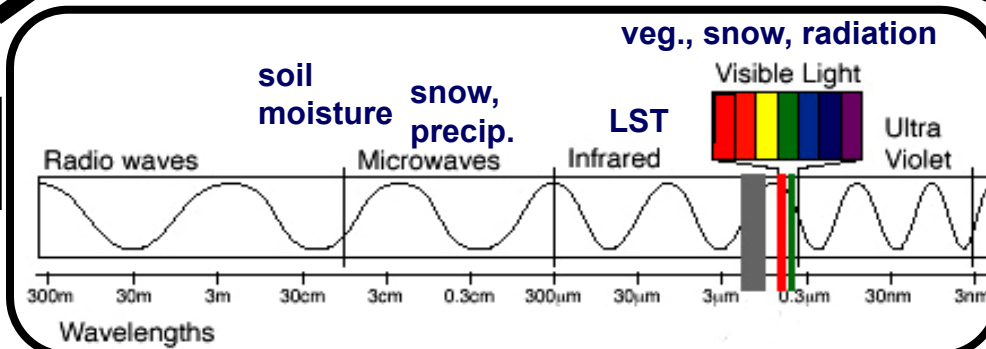
Radiation (CERES, CLARREO)



Land data assimilation system



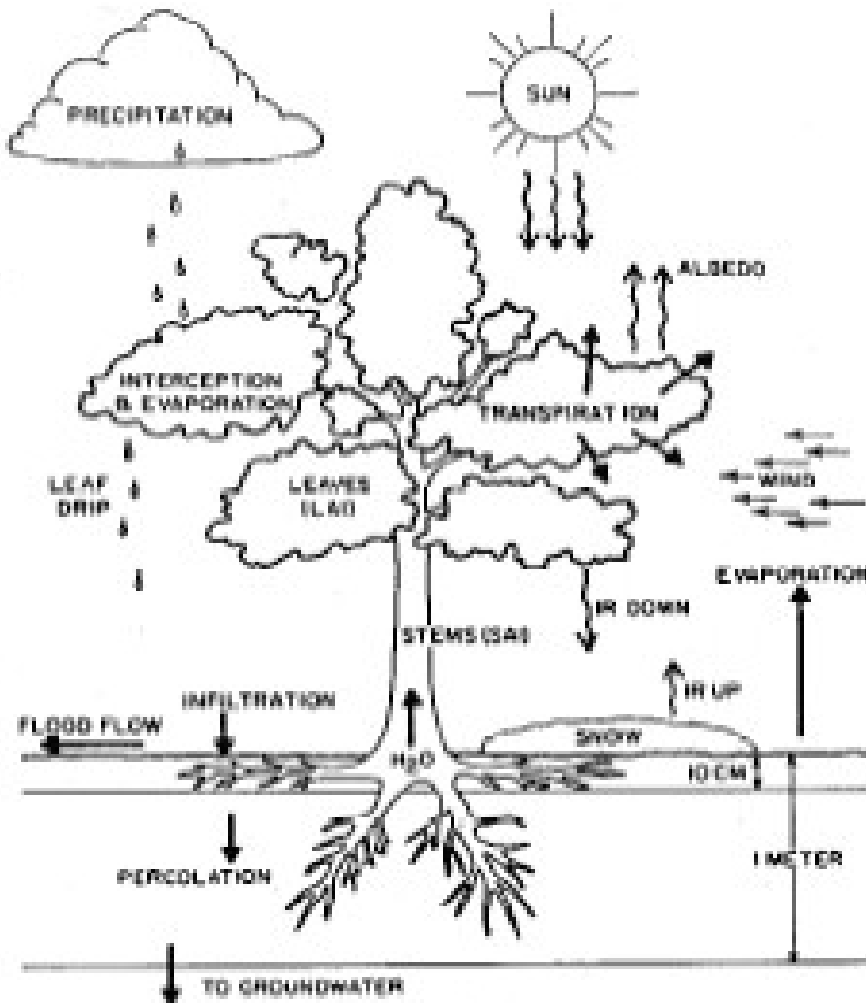
Terrestrial water storage (GRACE)



Vegetation/Carbon (AVHRR, MODIS, DESDynI, ICESat-II, HypSIRI, LIST, ASCENDS)



Land surface models



Surface water balance:

$$dS/dt = P - E - R$$

Surface energy balance:

$$dE/dt = G = R_s - LE - SH$$

Soil water redistribution:

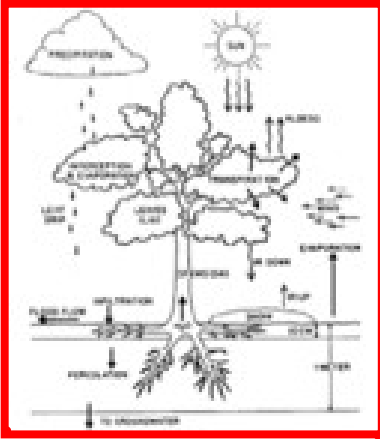
“Richards’ equation”

Soil heat redistribution:

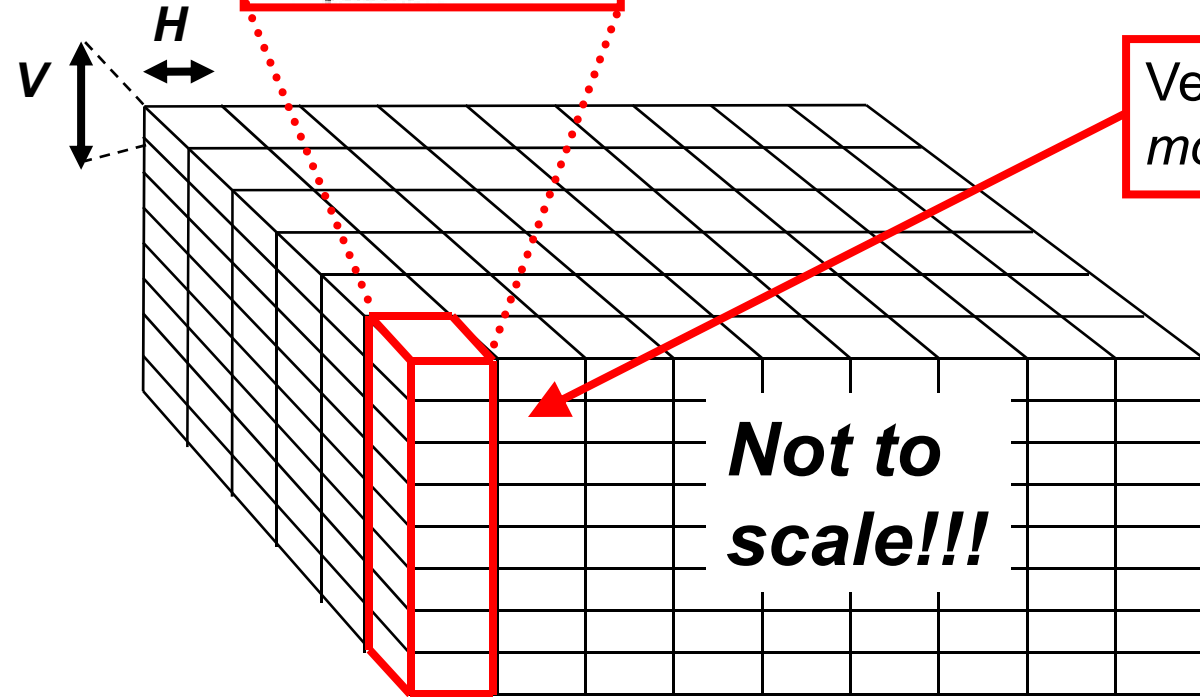
Heat diffusion equation



Temporal and spatial scales, discretization



Vertical:	~1 m
Horizontal:	10 m...100 km (watershed to global)
Time:	15 min time steps

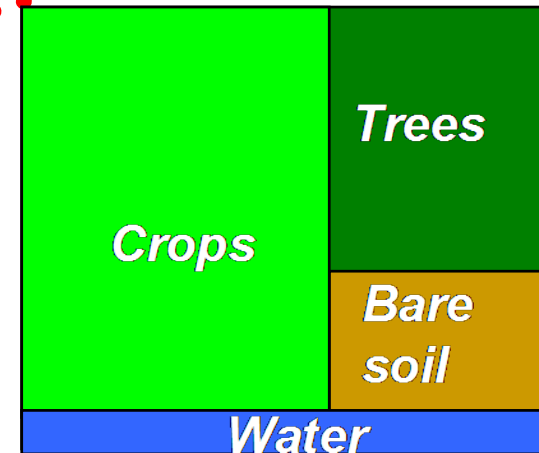


Vertical columns are modeled independently.

Not to scale!!!



Land surface heterogeneity



“Mosaic” approach
with lots of parameters...



Land surface models

Bucket model

BATS

LSM

OSU

NOAA

Noah model

NOAA/NCEP, NWS

Community Land Model

NCAR

Common Land Model

VIC (Variable Infiltration Capacity)

Princeton/U Washington

Toplats

Princeton

SiB (Simple Biosphere Model)

NASA

MOSAIC

NASA

PLACE

NASA

Catchment Land Surface Model

NASA

ISBA

Meteo-France

TESSEL

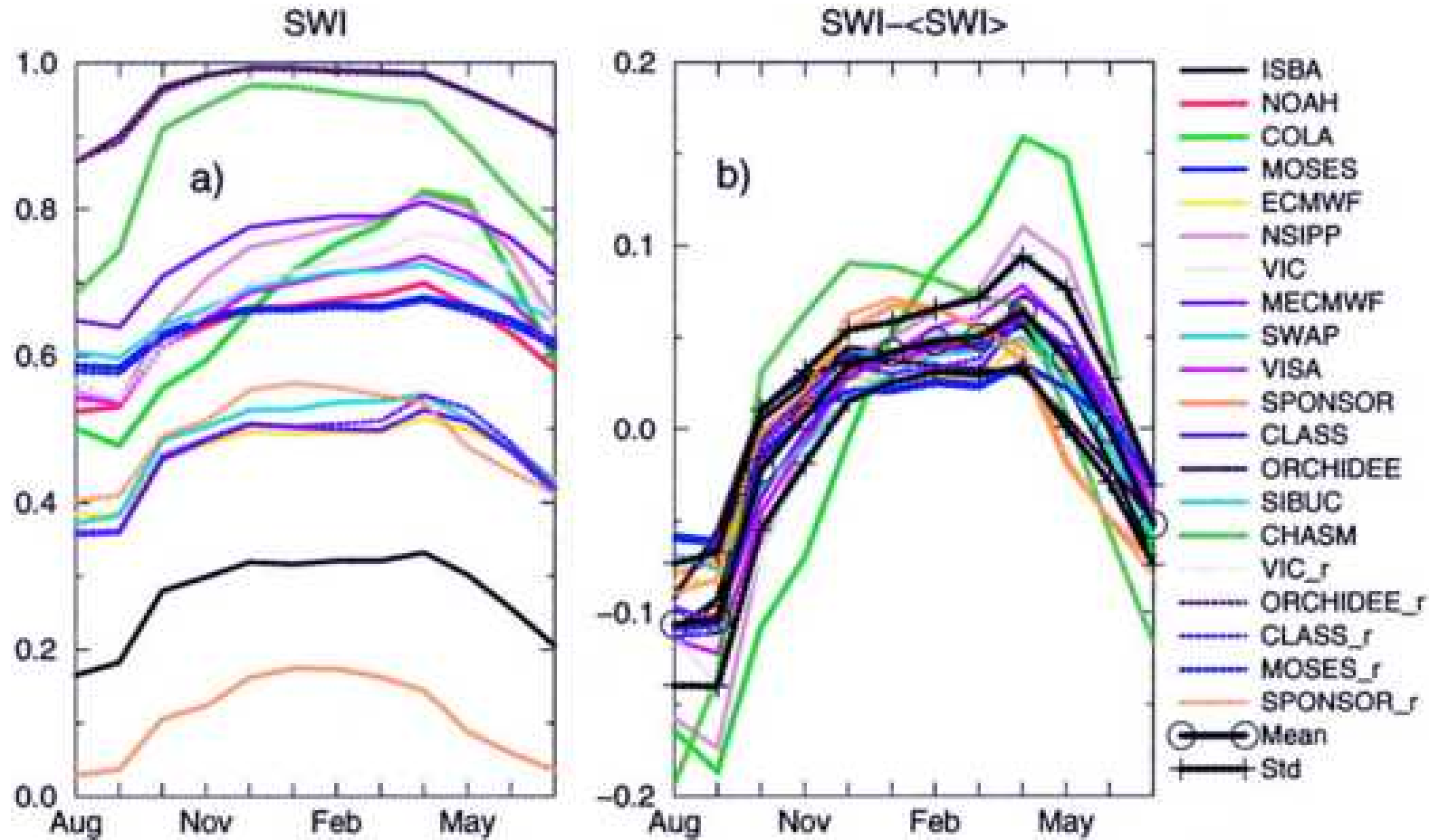
ECMWF

Terra

DWD

...and many more...

... there are as many land surface models as there are modelers...



Models agree on soil moisture only after “re-normalization”



Outline

Land surface observations and modeling

Land data assimilation methods

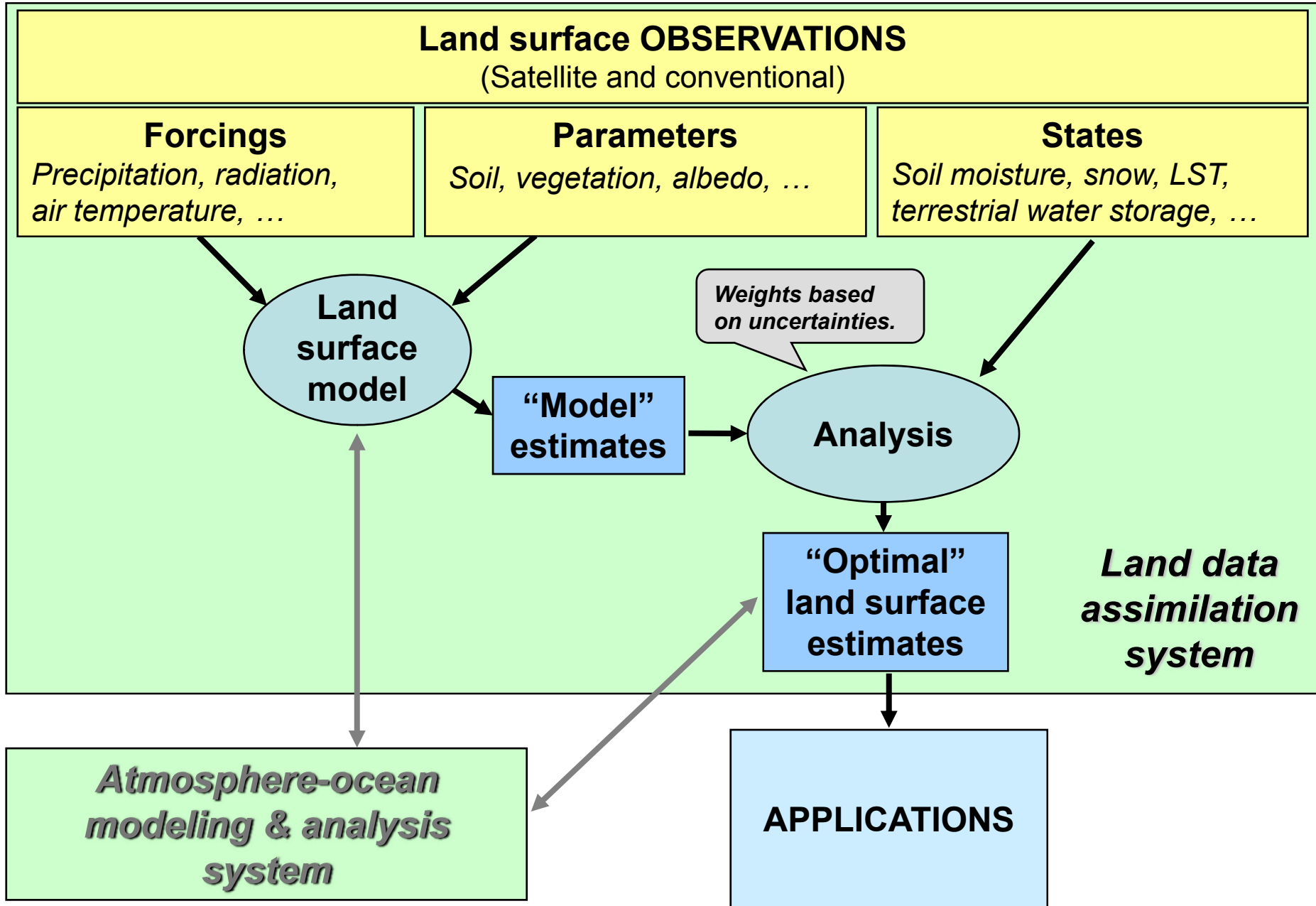
Examples – NOT a review!

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Error modeling and adaptive filtering

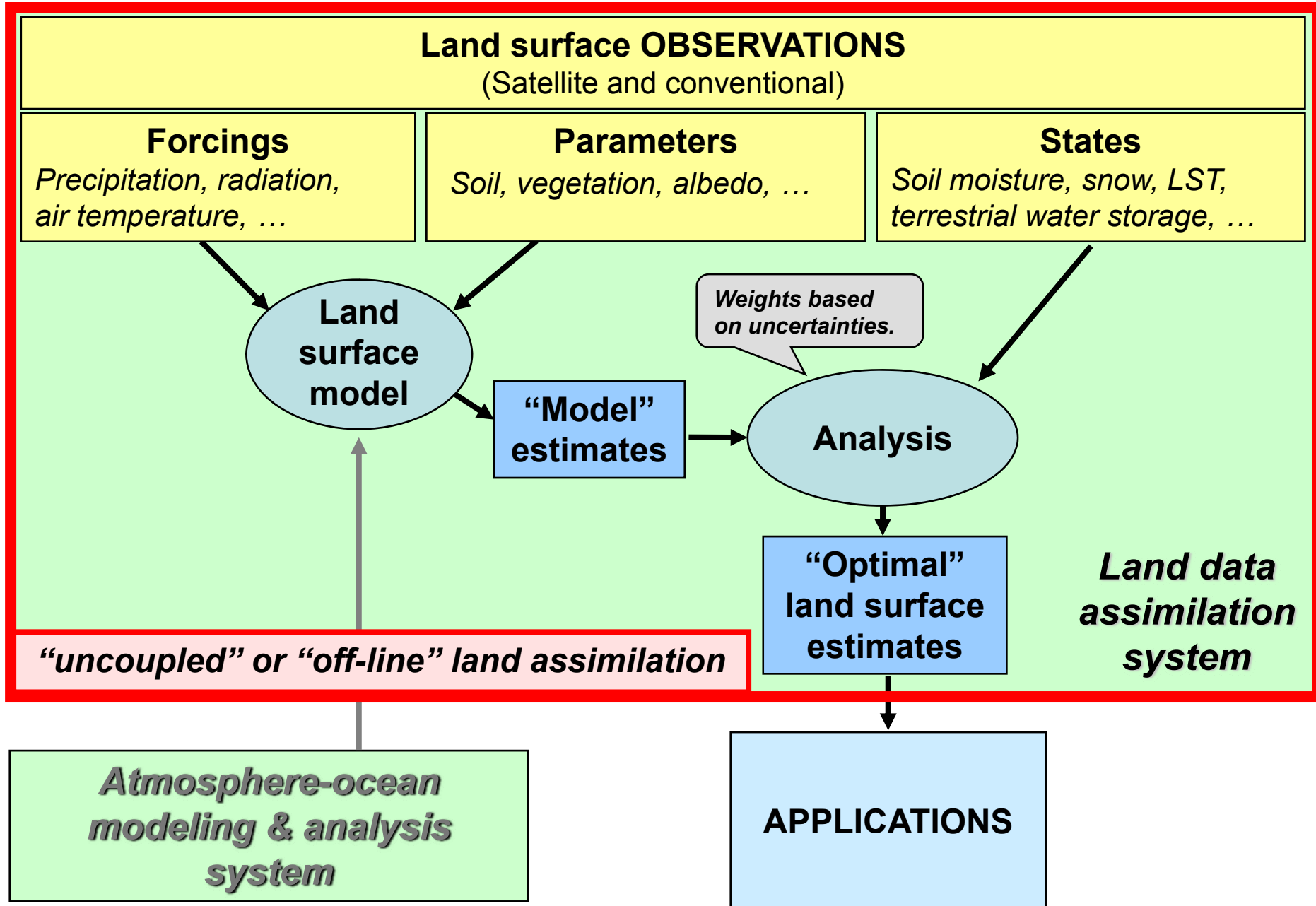


A generic land data assimilation system



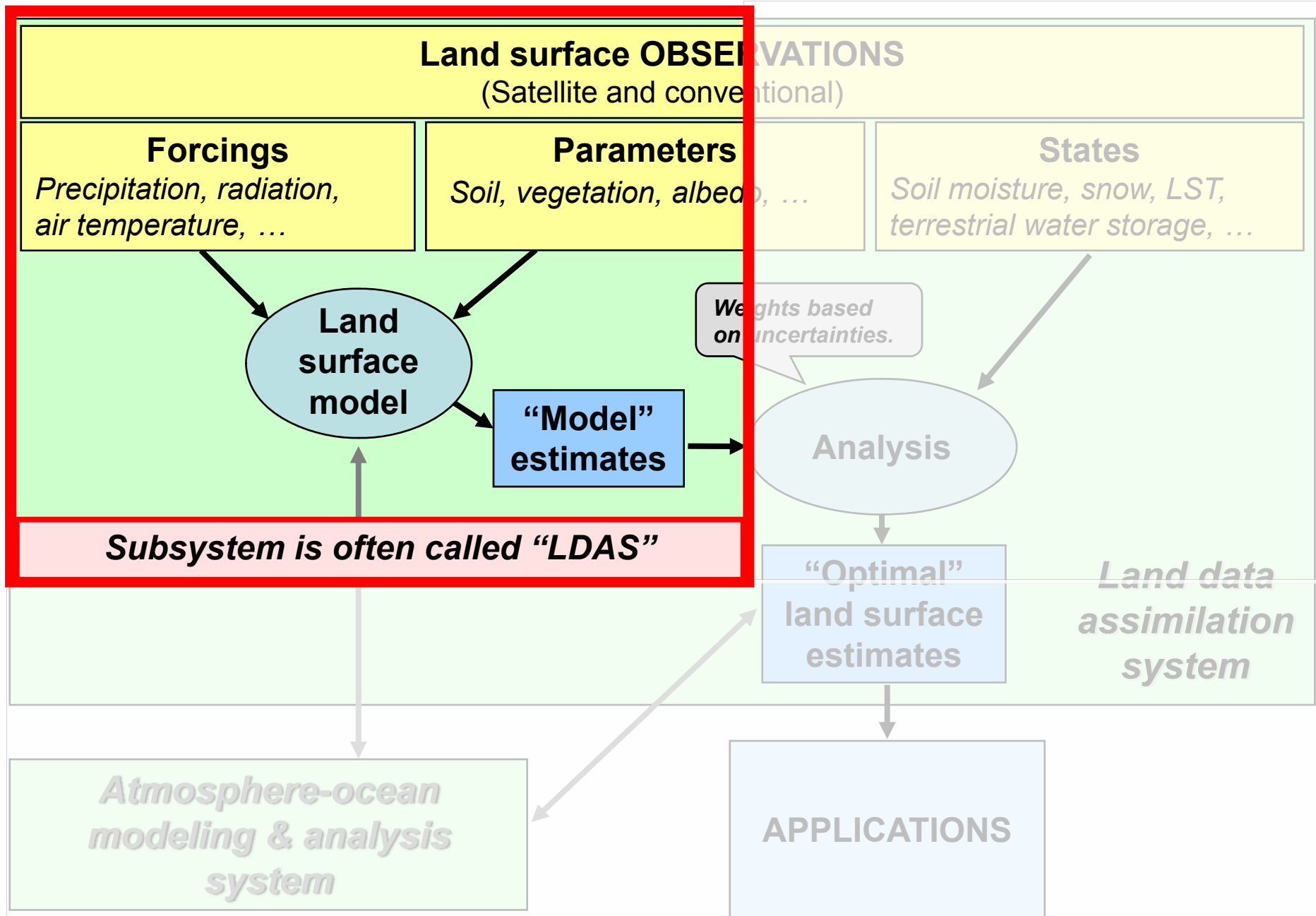


A generic land data assimilation system



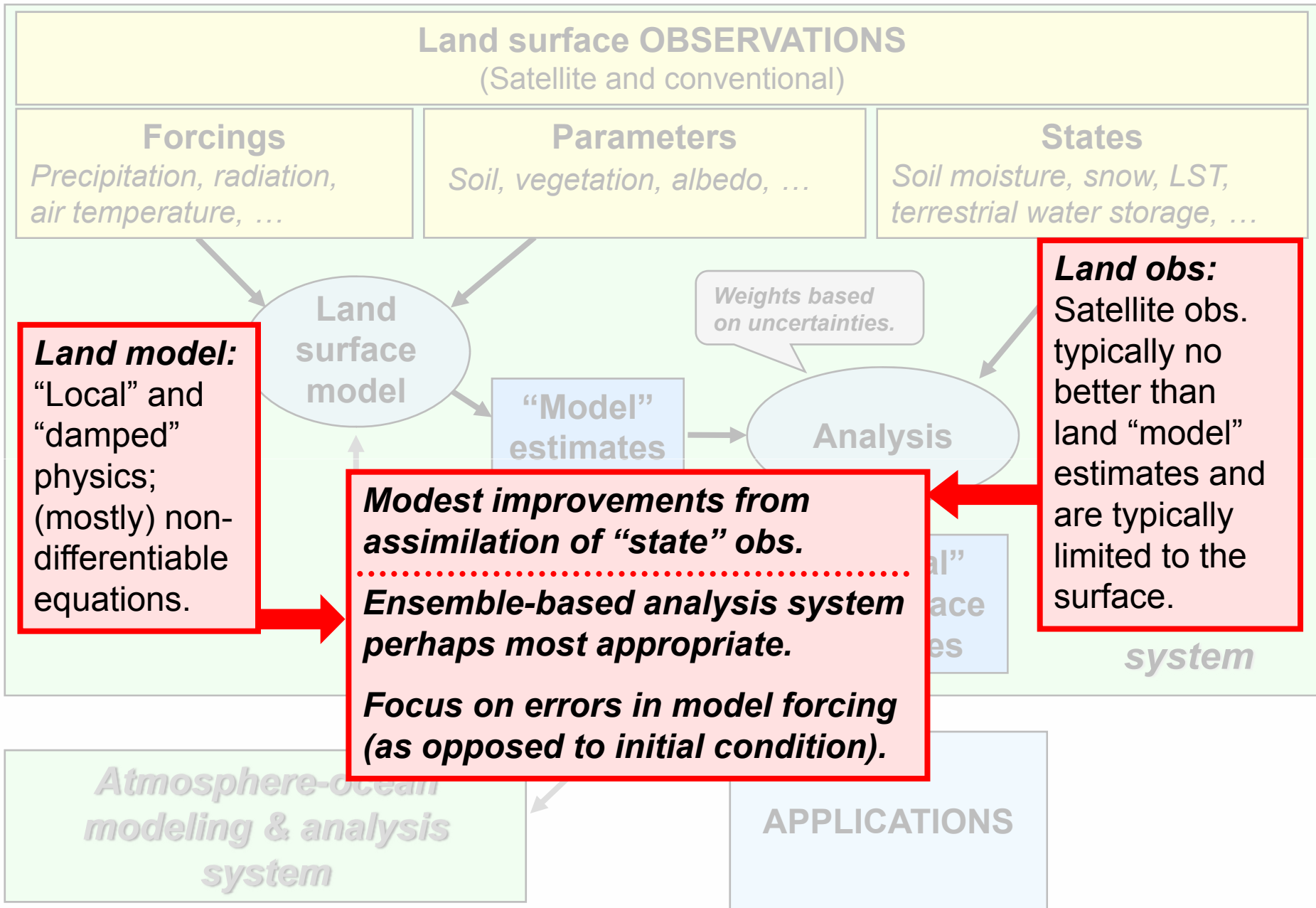


A generic land data assimilation system





What is special about land assimilation?





Land assimilation methods

Filters

Kalman filter approaches (KF, EKF, EnKF, ...)

Particle filters

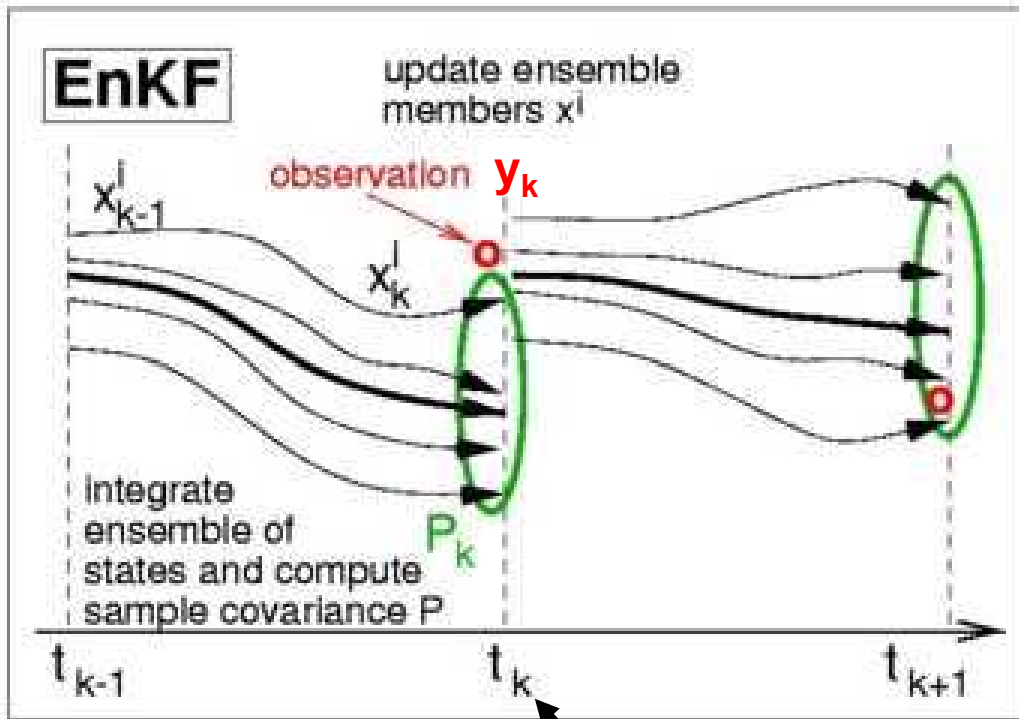
Smoothers

Strong- and weak-constraint variational (representers)

Ensemble-based smoothers



Ensemble Kalman filter (EnKF)



Nonlinear ensemble propagation approximates **model errors**.

Apply small **perturbations** to each ensemble member (model forcings and states) at every time step.

Linearized analysis update

x_k^i state vector (eg soil moisture)

P_k state error covariance

R_k observation error covariance

Propagation t_{k-1} to t_k :

$$x_k^{i-} = f(x_{k-1}^{i+}, e_k^i)$$

e = model error

Update at t_k :

$$x_k^{i+} = x_k^{i-} + K_k (y_k^i - x_k^{i-})$$

for each ensemble member $i=1 \dots N$

$$K_k = P_k (P_k + R_k)^{-1}$$

with P_k computed from ensemble spread



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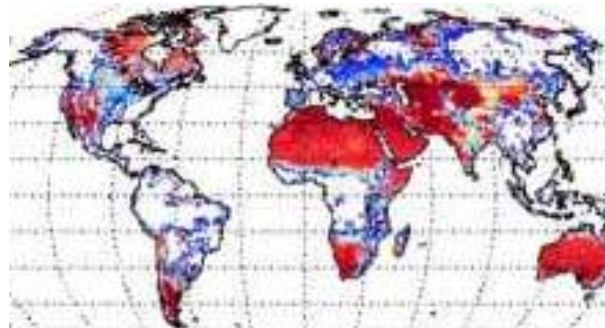
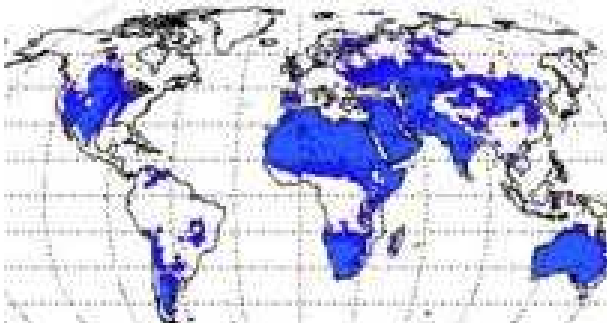
Global soil moisture data sets

Satellite retrievals (6-10 GHz microwave)

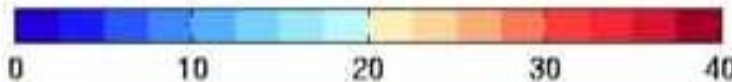
(upper 1.25cm, 40-140km, ~1-3 days)

SMMR (1979-87)

AMSR-E (2002-present)



Number of data per month



Soil moisture retrievals **not** available under dense vegetation, near open water, in frozen soil.

Also:

TRMM, Windsat; radar (active) sensors (ERS-1, ERS-2, ASCAT)

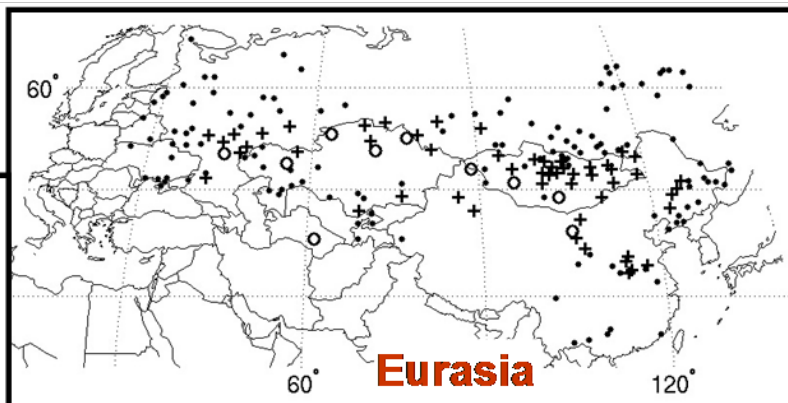
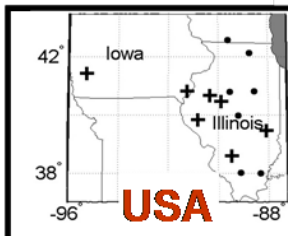
Soon:

SMOS, SMAP (1.4 GHz)

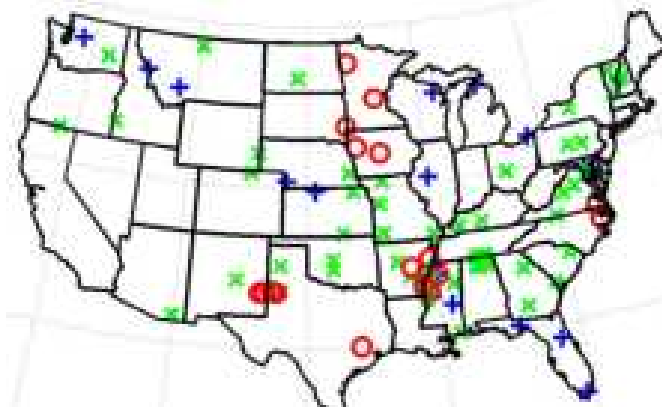
In situ data

(upper 5...10cm and profile, point scale, hourly - 10 days)

GSMDB



USDA SCAN

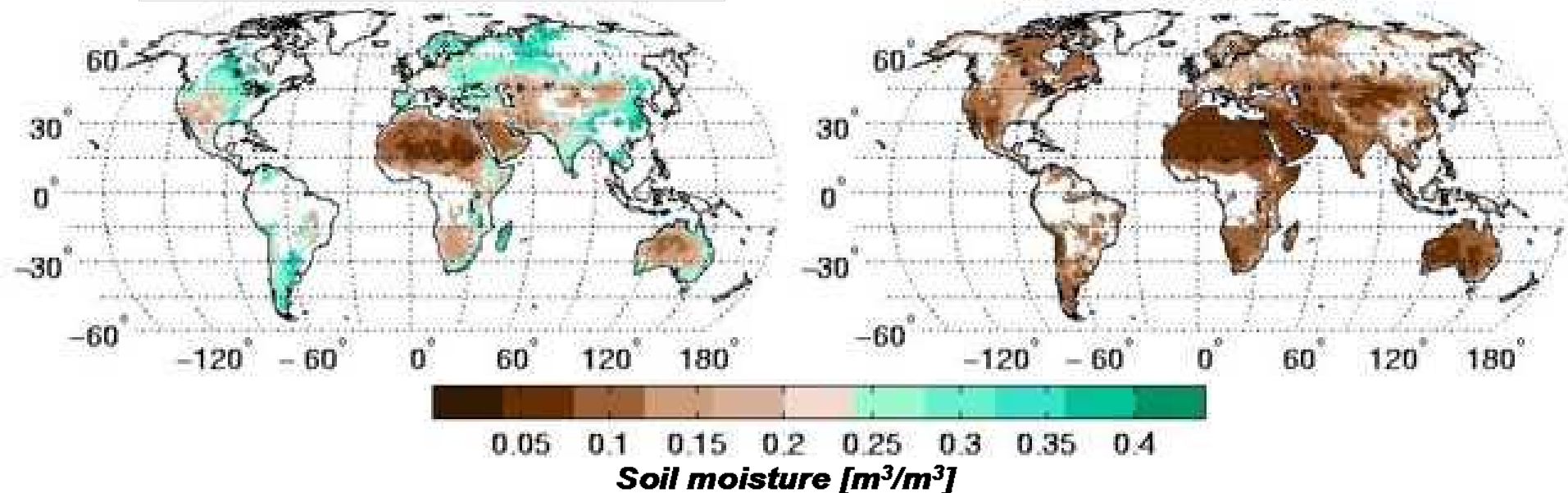




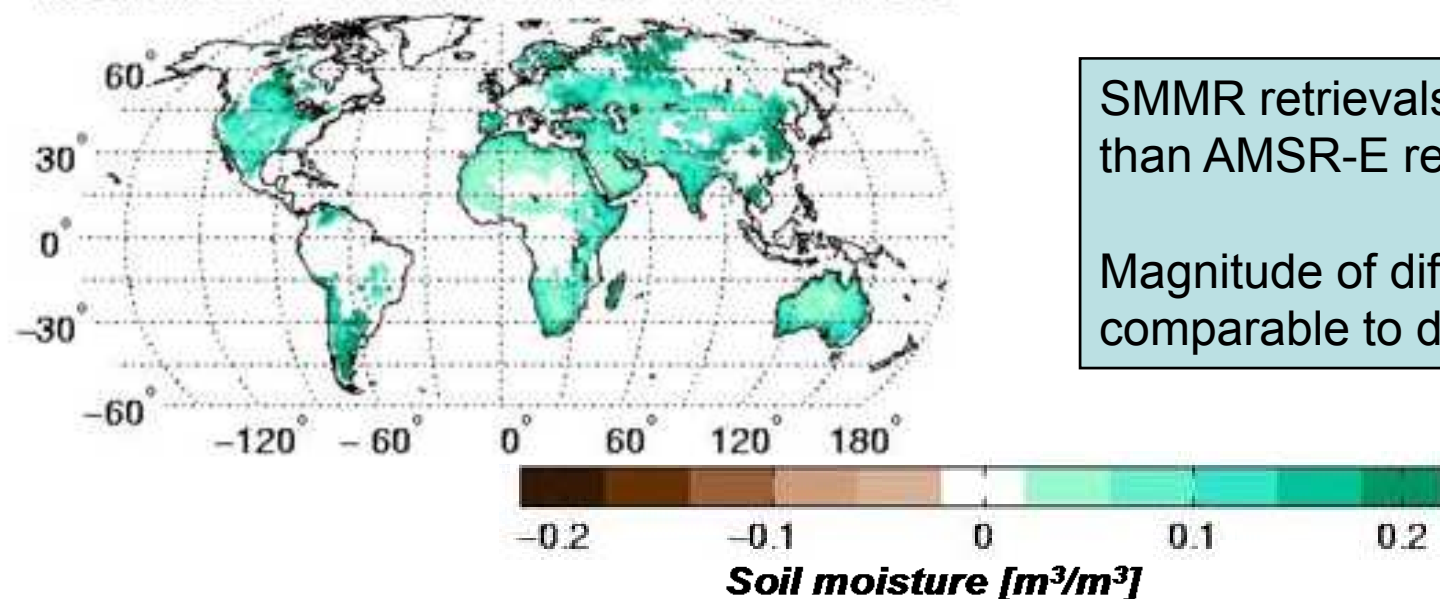
Satellite vs. satellite bias (time avg. soil moisture)

SMMR (1979-87)

AMSR-E (2002-05)



SMMR minus AMSR-E



SMMR retrievals **much** wetter than AMSR-E retrievals.

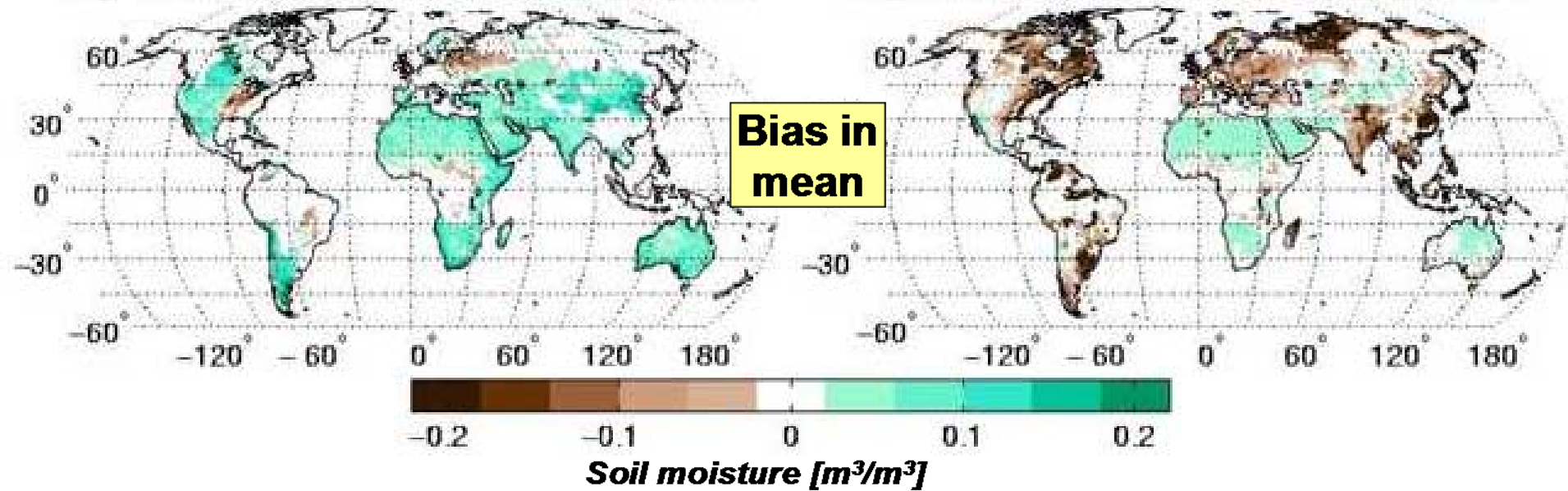
Magnitude of differences comparable to dynamic range.



Satellite vs. model bias

SMMR minus model (1979-87)

AMSR-E minus model (2002-05)



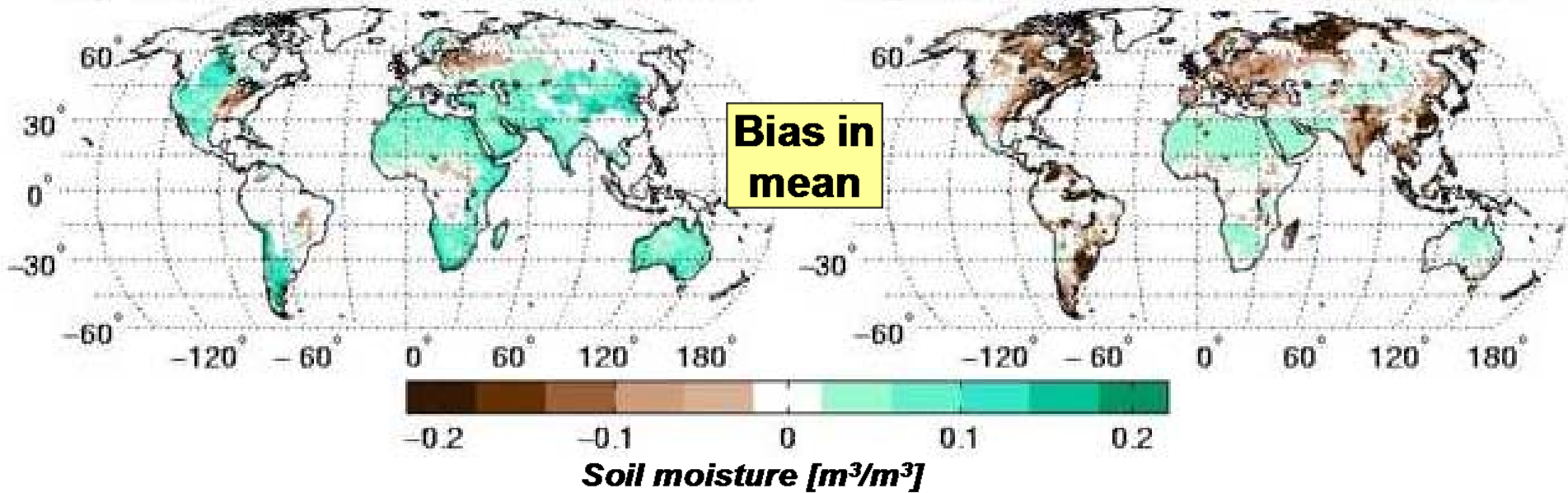


Satellite vs. model bias

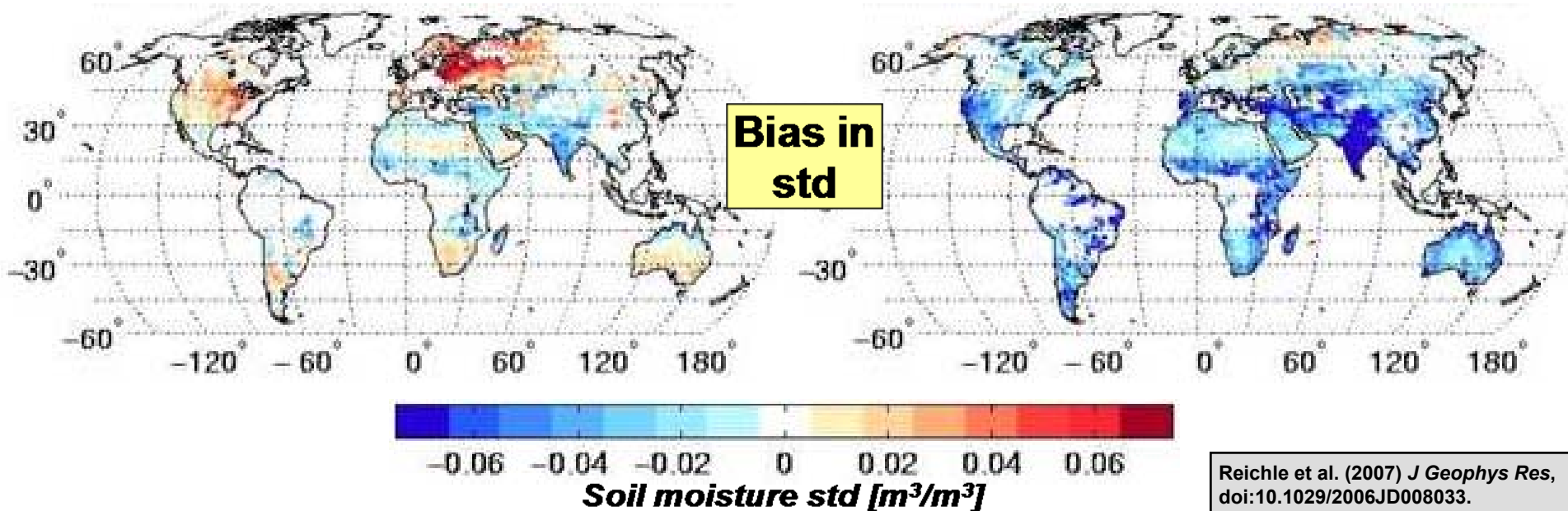
SMMR minus model (1979-87)

AMSR-E minus model (2002-05)

Bias in mean



Bias in std





Satellite vs. model bias

SMMR minus model (1979-87)

AMSR-E minus model (2002-05)

Bias in mean

1. Satellite retrievals exhibit **large and very different** global and regional **biases** in all moments relative to the model.
2. Absolute soil moisture from satellites and model agree **equally well** (or poorly...) with ground observations \Rightarrow no agreed climatology.
3. For model applications, focus on **normalized anomalies**.

\Rightarrow *Scale satellite data before assimilation into a model.*

Bias in std

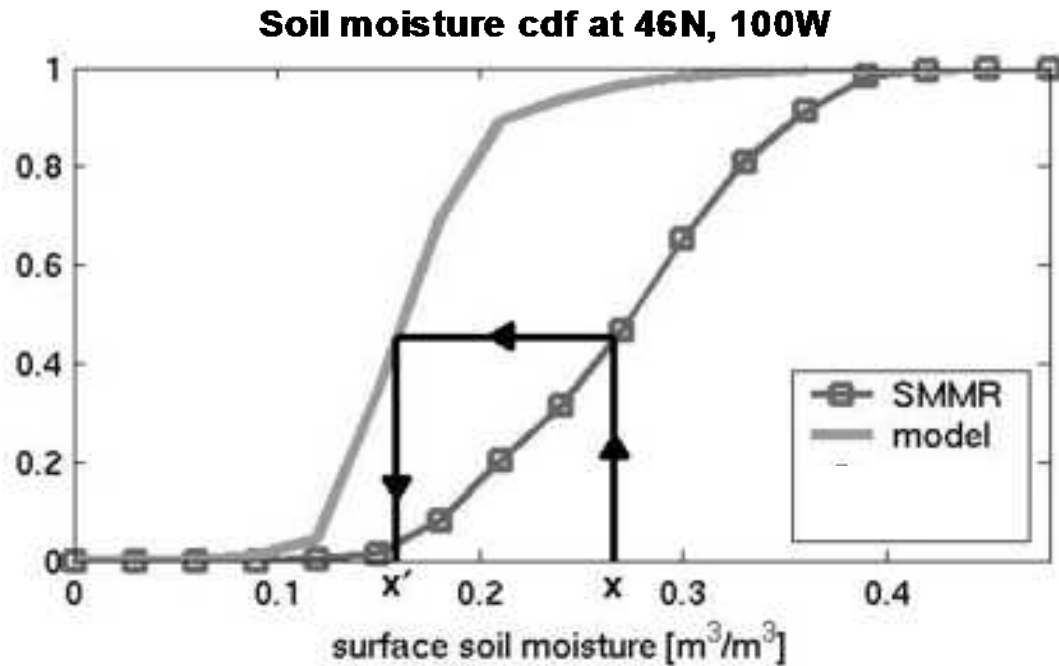


-0.06 -0.04 -0.02 0 0.02 0.04 0.06

Soil moisture std [m^3/m^3]



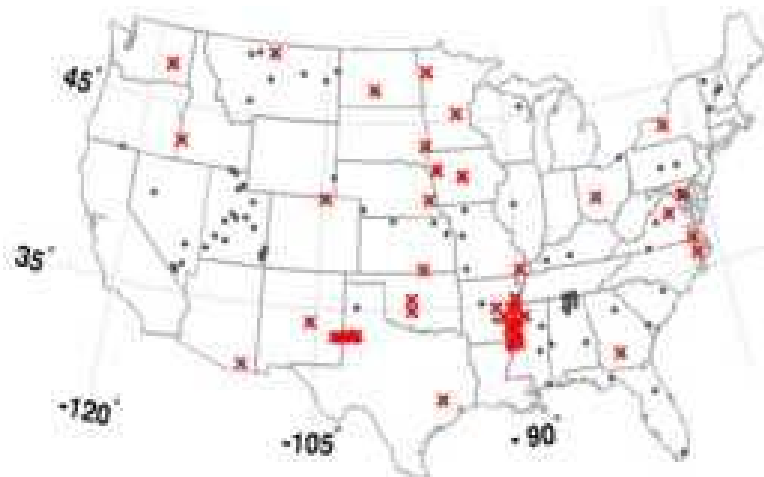
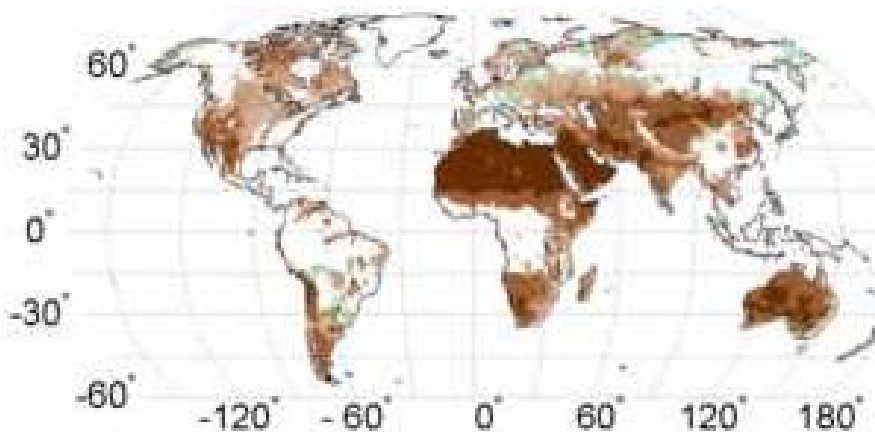
Soil moisture scaling for data assimilation



Assimilate percentiles.



Soil moisture assimilation



Assimilate AMSR-E surface soil moisture (2002-08) into NASA Catchment model



Validate with USDA SCAN stations (only 46 of 103 suitable for validation)

Root zone critical for applications but *not* observed by satellite.

Skill
(anomaly time series correlation coeff. with in situ data, with 95% confidence interval)

	N	Satellite	Model	Assim.
Surface soil moisture	46	.35±.01	.44±.01	.50±.01
<u>Root zone soil moisture</u>	41	n/a	<u>.43±.01</u>	<u>.49±.01</u>

- Assimilation product agrees better with ground data than satellite or model alone.
- Modest increase may be close to maximum possible with *imperfect* in situ data.
- Use data assimilation for generation of Soil-Moisture-Active-Passive (SMAP) “Level 4” product.



Soil-Moisture-Active-Passive (SMAP) mission design

Q: How uncertain can retrievals be and still add useful information in the assimilation system?

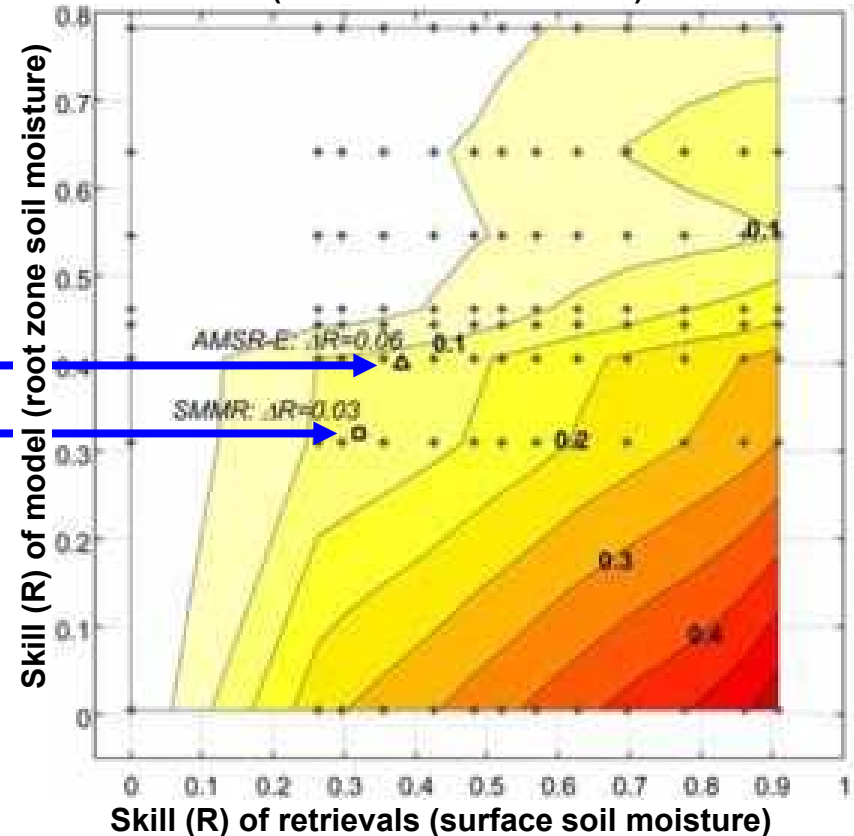
A: Synthetic data assimilation experiments.

Skill measured in terms of R
(=anomaly time series correlation coefficient against synthetic truth).

Each plus sign indicates result of one 19-year assimilation integration over Red-Arkansas domain.

AMSR-E (Δ):
 $\Delta R=0.06$
SMMR (\square):
 $\Delta R=0.03$

Skill improvement of assimilation over model (ΔR)
(root zone soil moisture)



Results

- Assimilation of (even poor) soil moisture retrievals adds skill (relative to model product).
- Published AMSR-E and SMMR assimilation products consistent with expected skill levels.
- Derive error budget analysis for SMAP.



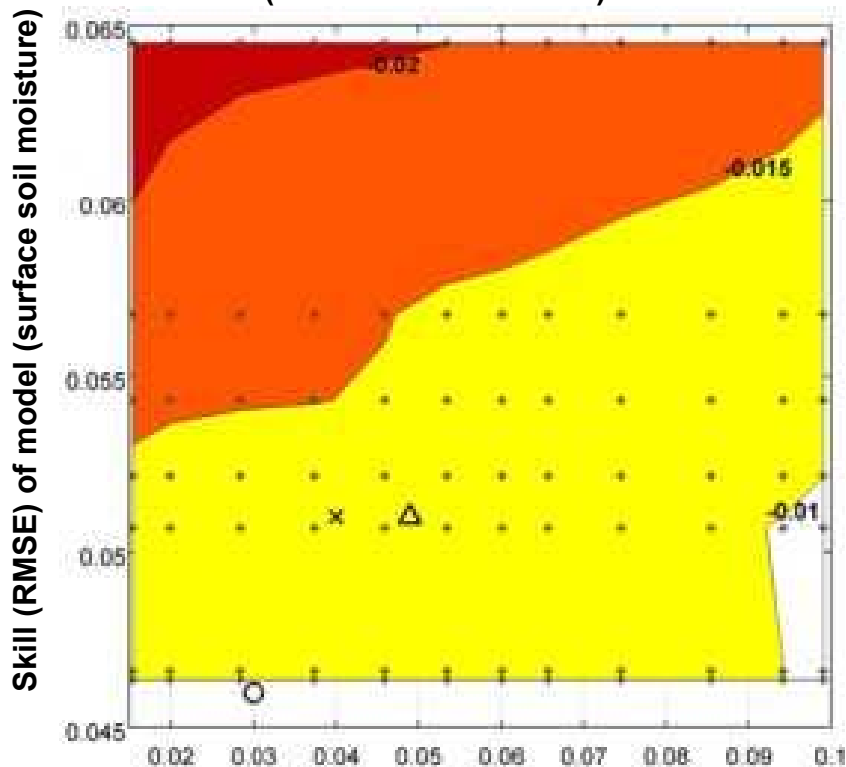
Uncertainty estimates: OSSE approach

anomaly RMSE [m³/m³]

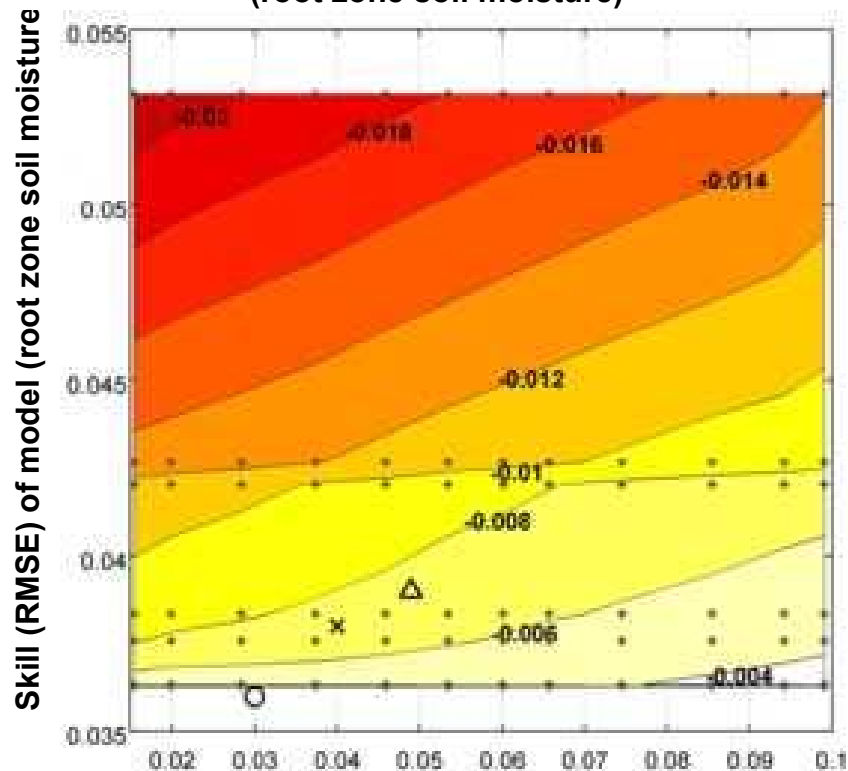
surface soil moisture

root zone soil moisture

Skill *improvement* of assimilation over model (Δ RMSE)
(surface soil moisture)



Skill *improvement* of assimilation over model (Δ RMSE)
(root zone soil moisture)



- = L4_SM (high skill)
- × = L4_SM (low skill)
- △ = AMSR-E

Symbols indicate (actual or estimated) skill for satellite observations and land modeling systems.

Anomalies ≡ Daily data with mean seasonal cycle removed



Multi-model soil moisture assimilation



How does land model formulation impact assimilation estimates of root zone soil moisture?

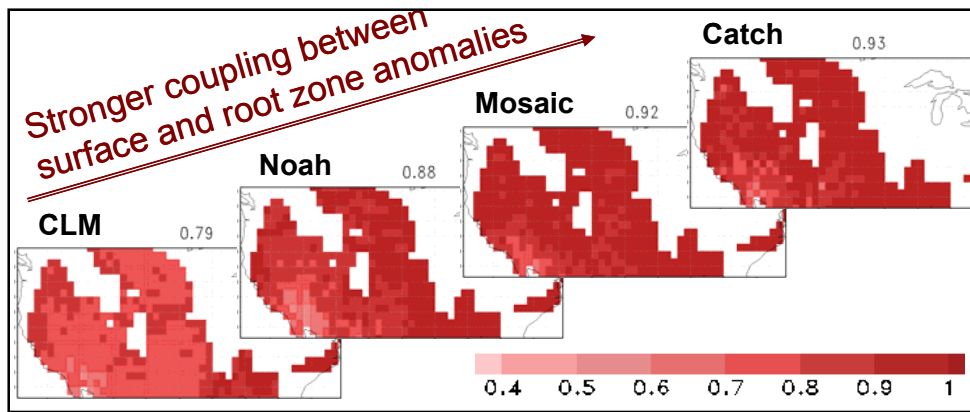
Normalized ROOT ZONE soil moisture improvement from assimilation of surface soil moisture

		Synthetic observations from				Avg
		Catch	Mos	Noa	CLM	
Model	Catch	0.71	0.54	0.36	0.38	0.50
	Mos	0.55	0.69	0.31	0.33	0.47
	Noa	0.43	0.43	0.36	0.26	0.37
	CLM	0.11	0.21	0.10	0.45	0.22
Avg		0.45	0.47	0.28	0.36	0.39

Catchment and Mosaic work better for assimilation than Noah or CLM.

Catchment or MOSAIC "truth" easier to estimate than Noah or CLM "truth".

Stronger coupling between surface and root zone provides more "efficient" assimilation of surface observations.





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Examples – NOT a review!

- Soil moisture
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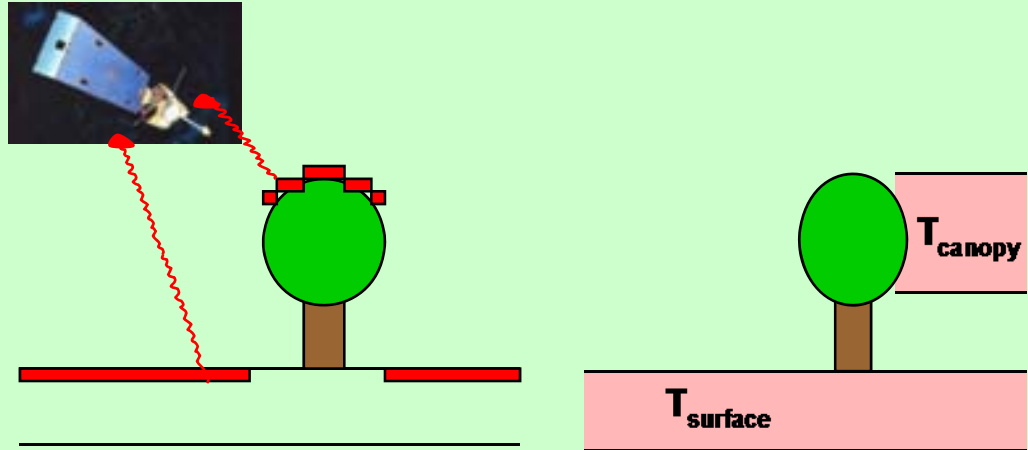
Error modeling and adaptive filtering



Land surface temperature (LST) assimilation

Good news: Abundance of LST retrievals from *infrared* and *microwave* sensors on *geostationary* and *polar-orbiting* platforms (NOAA-xx, MODIS, GOES, METEOSAT, GMS,...)

Problem 1:
Satellite and model LST
inconsistent in vertical.



Problem 2:
Satellite and model LST
inconsistent in horizontal.



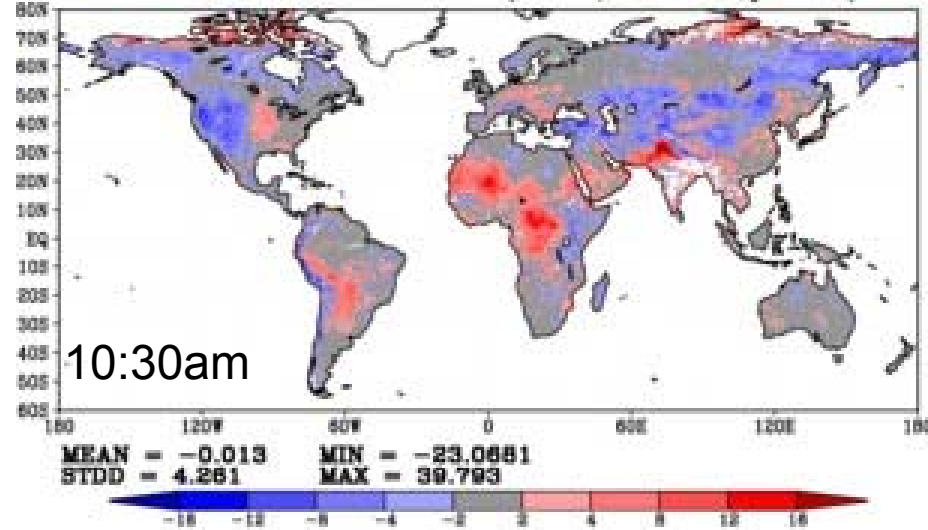
Problem 3: Satellite LST
sensor- or algorithm-specific.



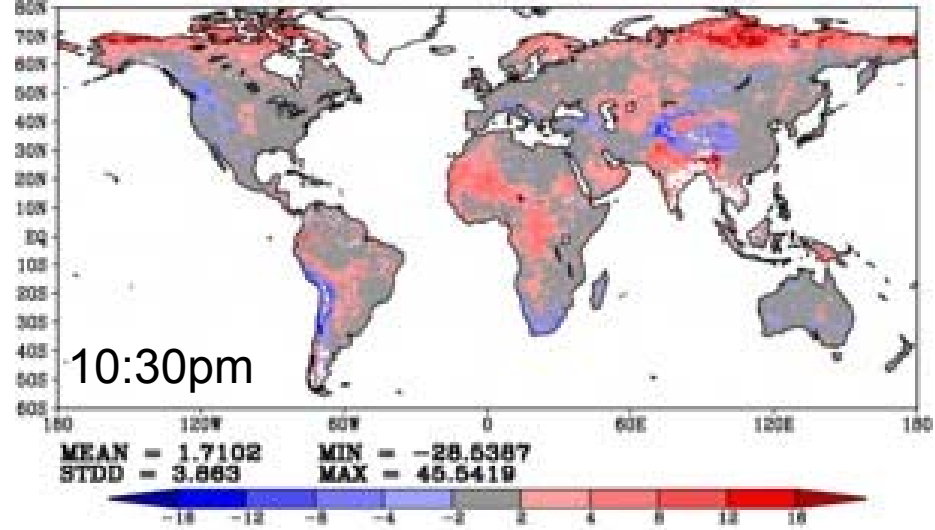
An example of "model" versus retrieval differences

July 2004 LST: GEOS-5 DAS *minus* MODIS
[Bosilovich et al, NASA/GMAO, Mar 2008]

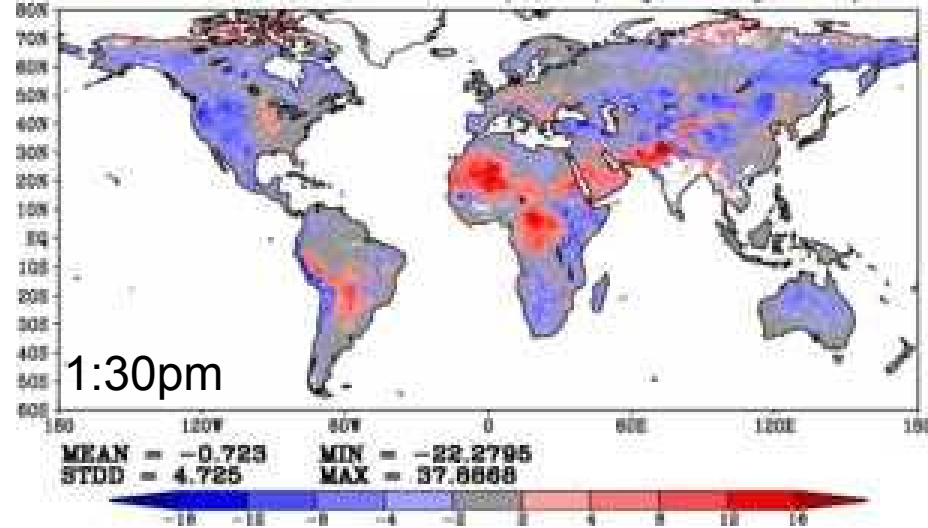
GEOS5 - MODIS Jul 2004 (LSTHQ Terra Day Pass)



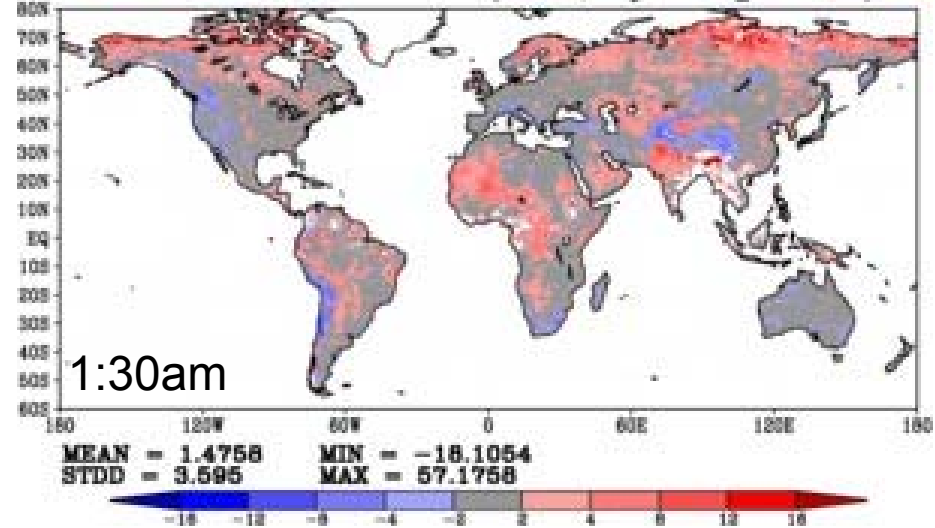
GEOS5 - MODIS Jul 2004 (LSTHQ Terra Night Pass)



GEOS5 - MODIS Jul 2004 (LSTHQ Aqua Day Pass)



GEOS5 - MODIS Jul 2004 (LSTHQ Aqua Night Pass)





Bias estimation approach

- 1.) *Off-line (a priori) scaling between climatology of obs. and land model:*
Match mean & var for each calendar month and time of day
+ No assumption whether model or observations are biased.
+ Easy to implement in pre-processing.
– Static (cannot adjust to changes in bias).

- 2.) *Dynamic model bias estimation (Dee and da Silva, 1998):*
– Assume obs. climatology is correct and the model is biased.
+ Dynamic (adjusts to changes in bias).

Standard Kalman filter: $x^+ = x^- + K_x(y - Hx^-)$
 $K_x = P_x H^T (H P_x H^T + R)^{-1}$

Bias estimation: $b^+ = b^- - K_b(y - H(x^- - b^-))$ 2nd Kalman filter
Assume: $P_b \sim P_x \rightarrow K_b = \gamma K_x$

Use *regular Kalman filter machinery* to update bias.

Bias estimate is effectively time average of increments.

Options for diurnal and semi-diurnal bias parameterization.

γ and a relaxation time scale are tuning parameters.



Land surface temperature (LST)

Assimilate:

ISCCP = International Satellite Cloud Climatology Project
Archive of Tskin retrievals from many geo-stationary and polar-orbiting platforms (NOAA-xx, GOES, METEOSAT,...)
- 3-hourly, mapped to 1 deg lat-lon grid
- clear-sky only!



Validate:

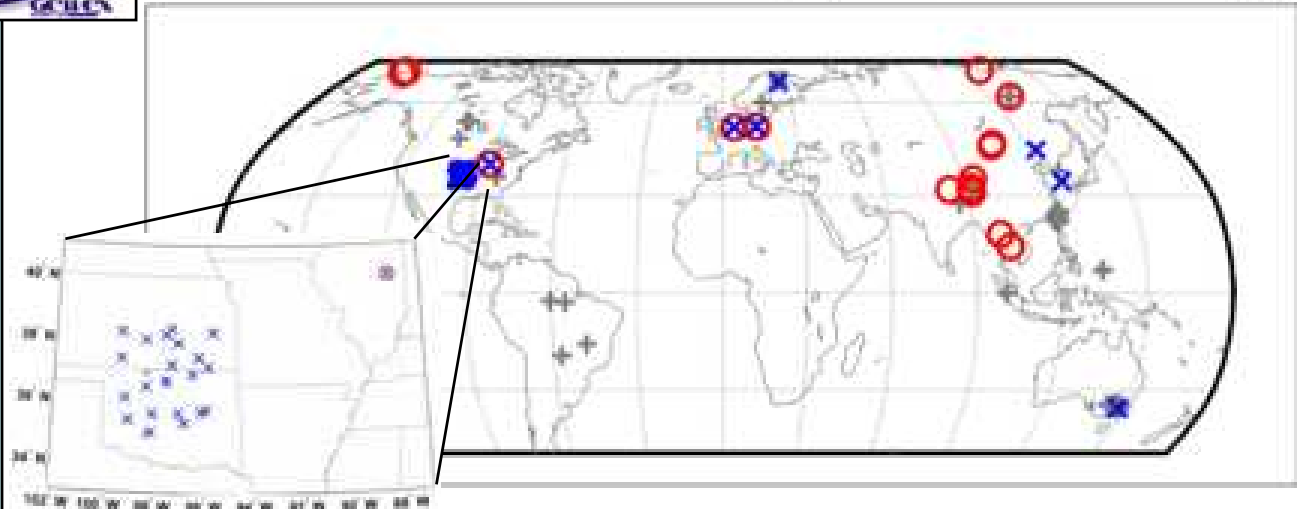
Coordinated Energy and Water Cycle Observations Project



Period 3&4:
1 Oct '02 – 31 Dec '04
(27 months)

51 stations w/ Tskin and/or sensible/latent heat flux obs

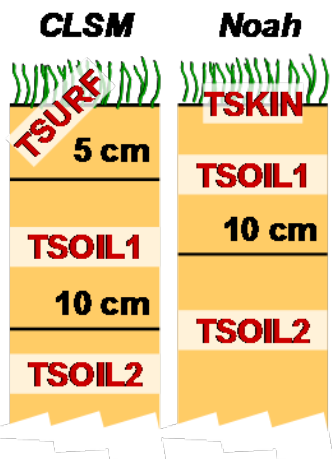
CEOP3/4 stations w/ obs of Tskin (o) and/or surface fluxes (x)



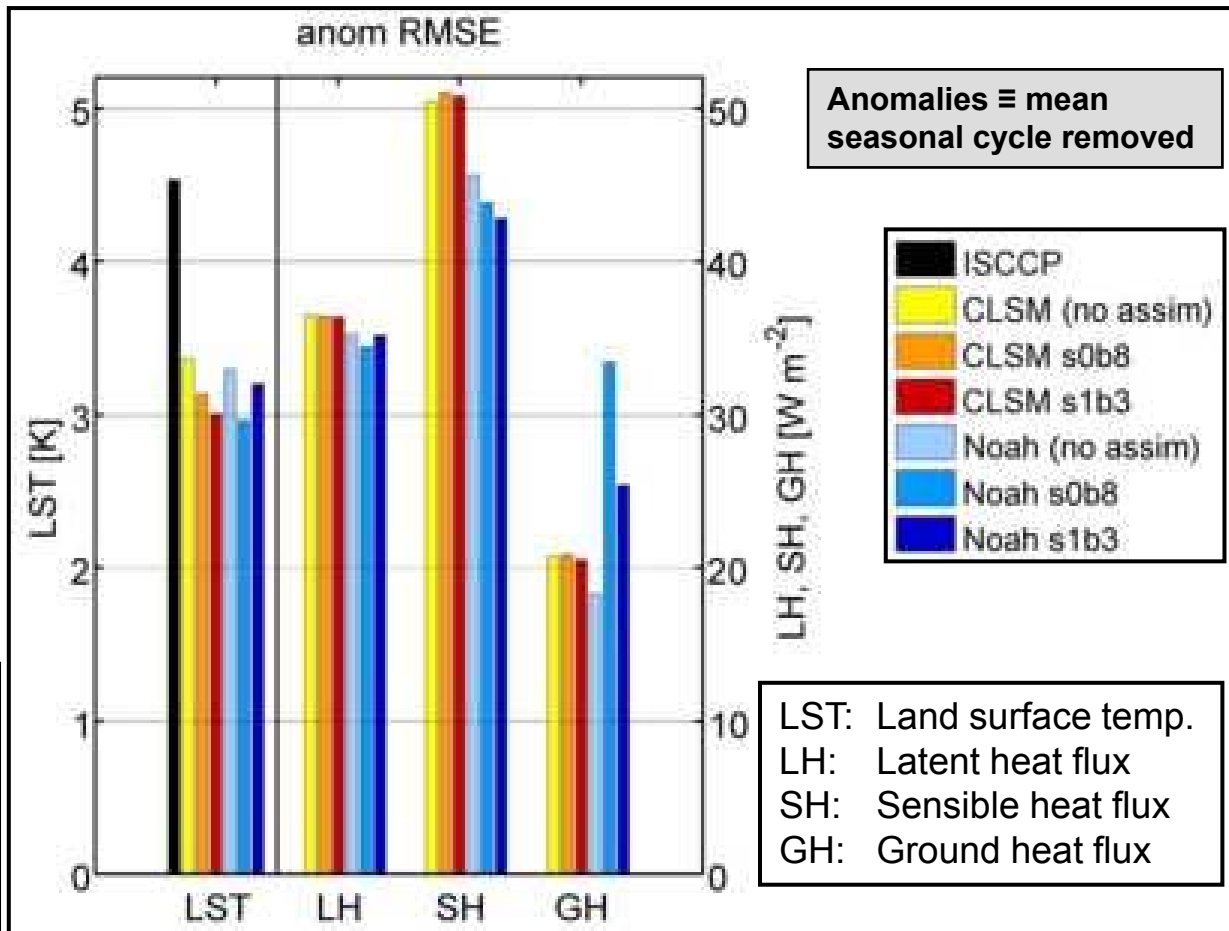
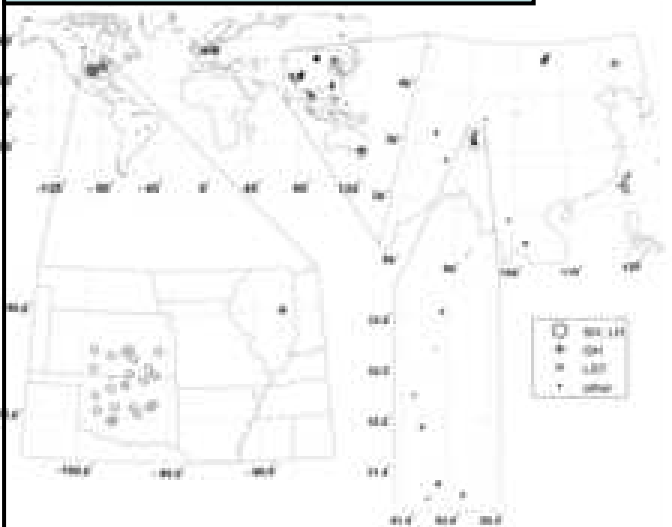


Land surface temperature (LST) assimilation

Assimilate ISCCP LST into off-line land models: Catchment (CLSM) & Noah.



Validate against CEOP obs. (48 stations; 2003-2004).



“Model” LST much better than ISCCP.

Assimilation reduces anomaly RMSE by ~ 0.3 K.

Bias estimation necessary.

Model formulation impacts assimilation strategy.



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Snow cover assimilation

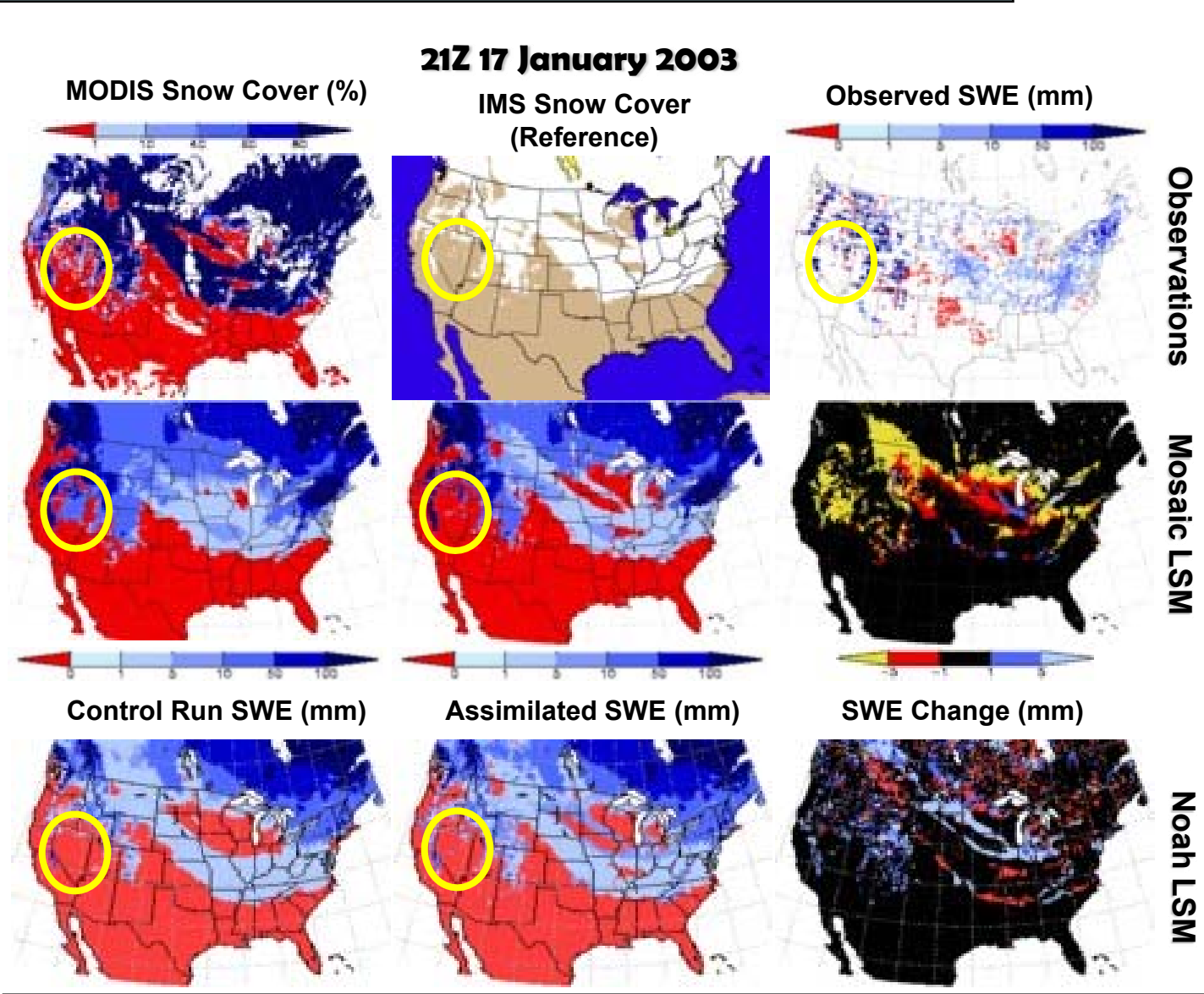
Use MODIS snow cover to update model snow water equivalent (SWE)

Snow cover data are **binary**
→ “rule-based” assimilation

Model fills spatial and temporal data gaps, provides continuity and quality control.

Assimilation output

- agrees better with IMS snow cover (top middle)
- contains more information (~hourly SWE) than MODIS (~daily snow cover)

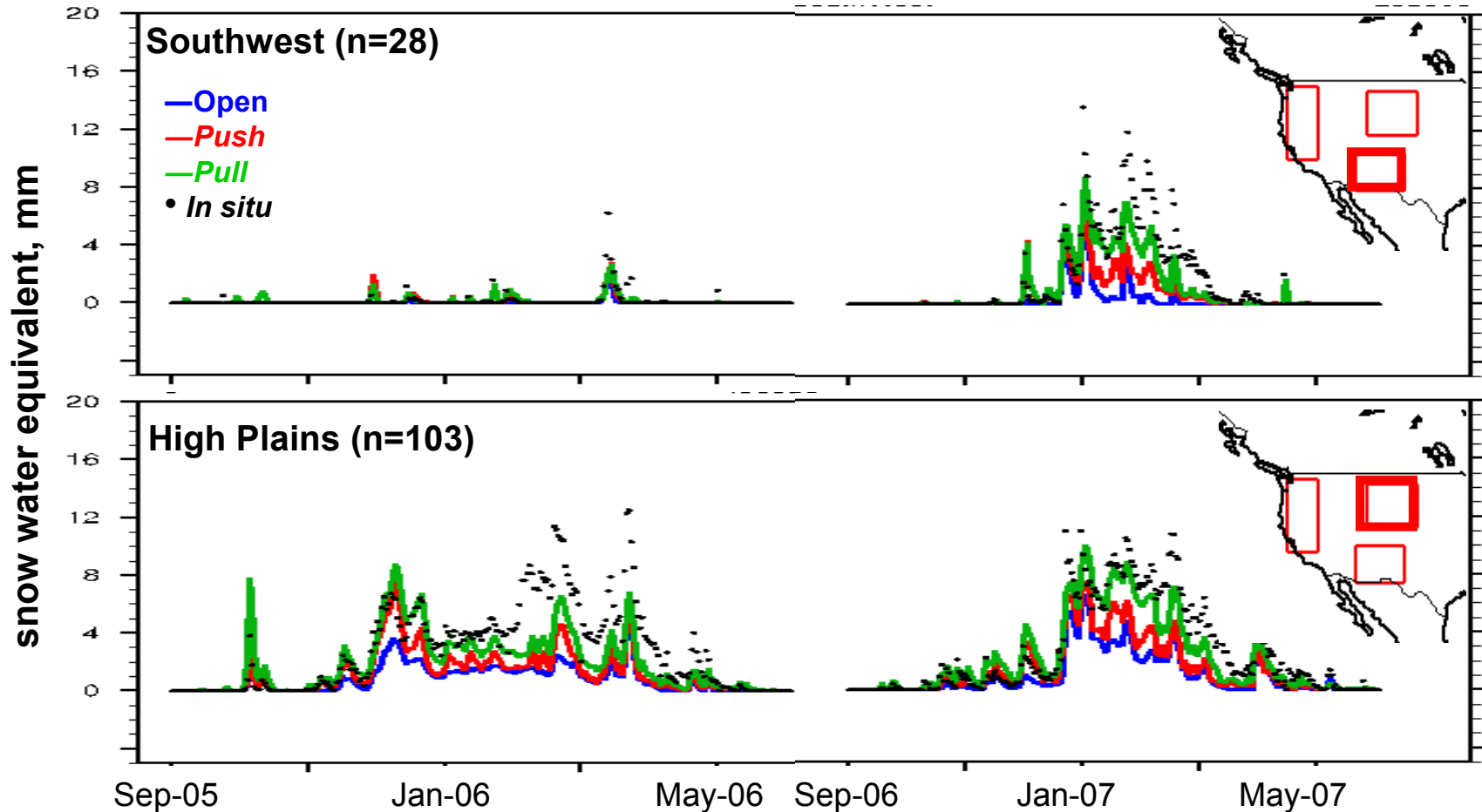




Snow cover assimilation

Forward-looking “pull” algorithm (smoother):

- Assess MODIS snow cover 24-72 hours ahead
- Adjust air temperature (rain v. snowfall, snow melting v. frozen)



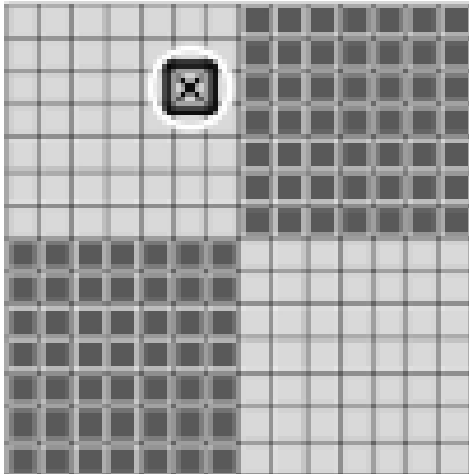


SWE assimilation and downscaling

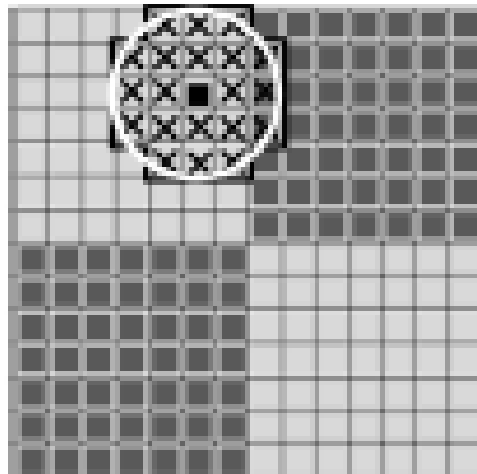
Assimilate SWE retrievals from satellites (~25 km) into high-resolution (1 km) land surface model

Questions:

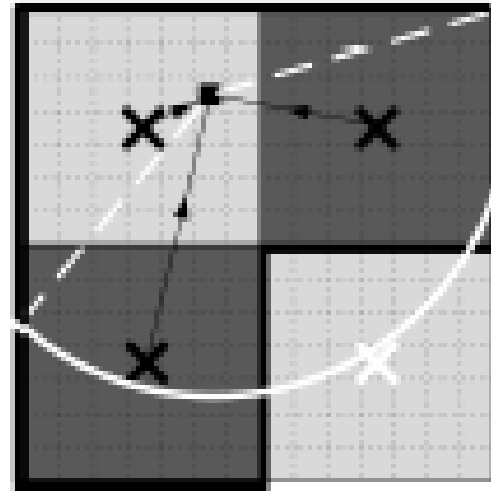
- 1) Disaggregate prior to assimilation?
- 2) Use local and/or remote observations?



disagg. obs prior to assim.
1D update



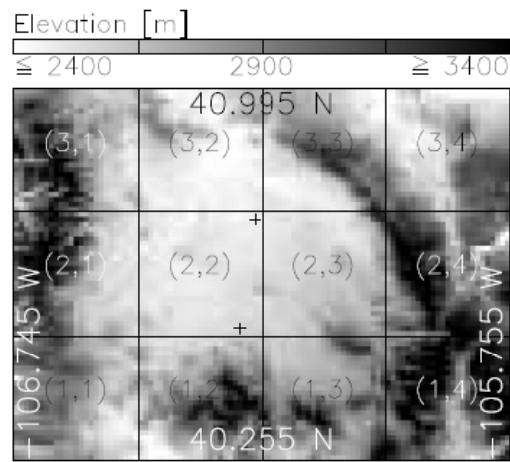
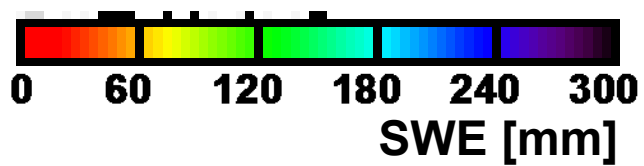
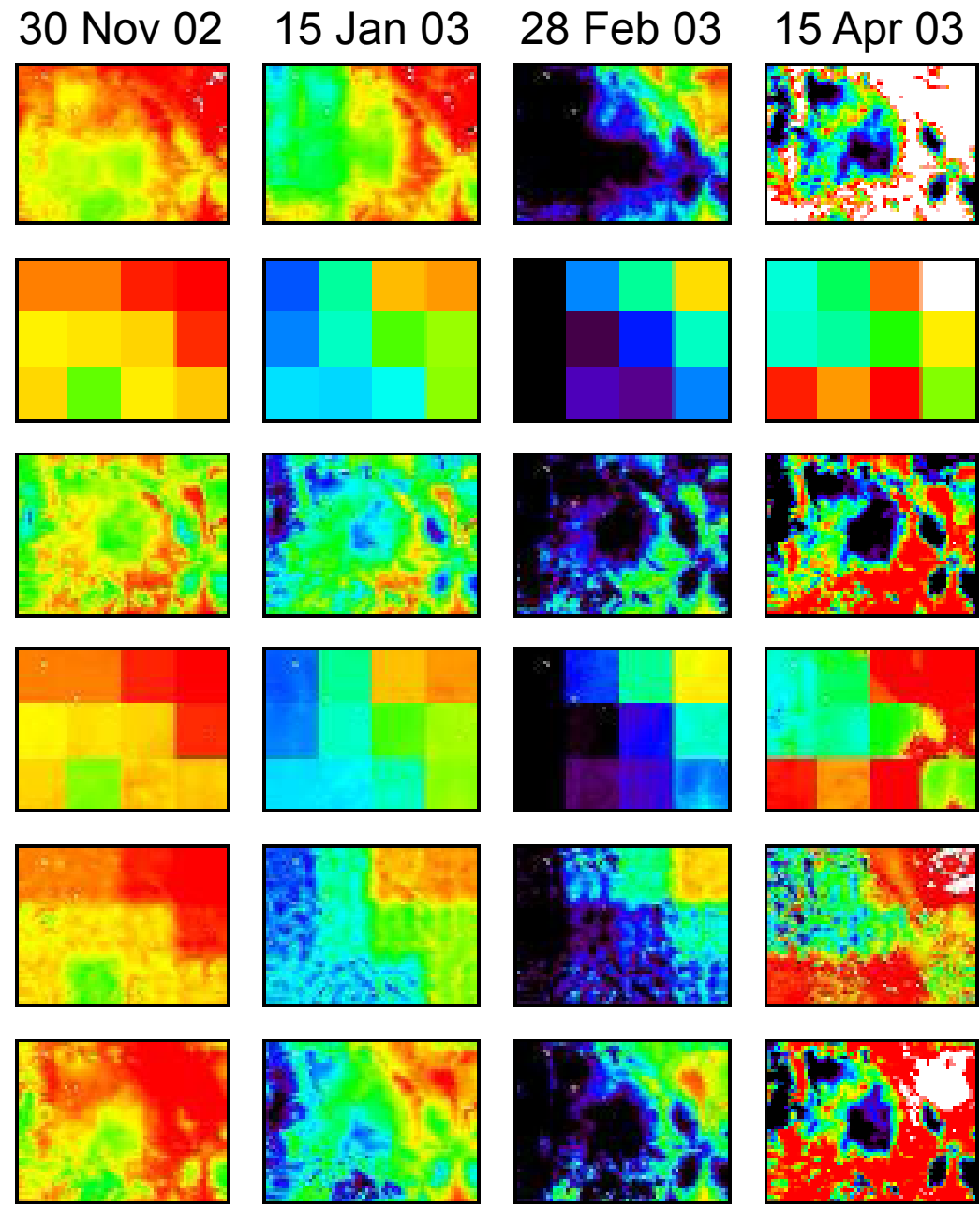
3D update



Obs. operator maps
(fine-scale) model SWE to
(coarse-scale) observations,
3D update



SWE assimilation and downscaling



Best:
obs. operator,
3D update

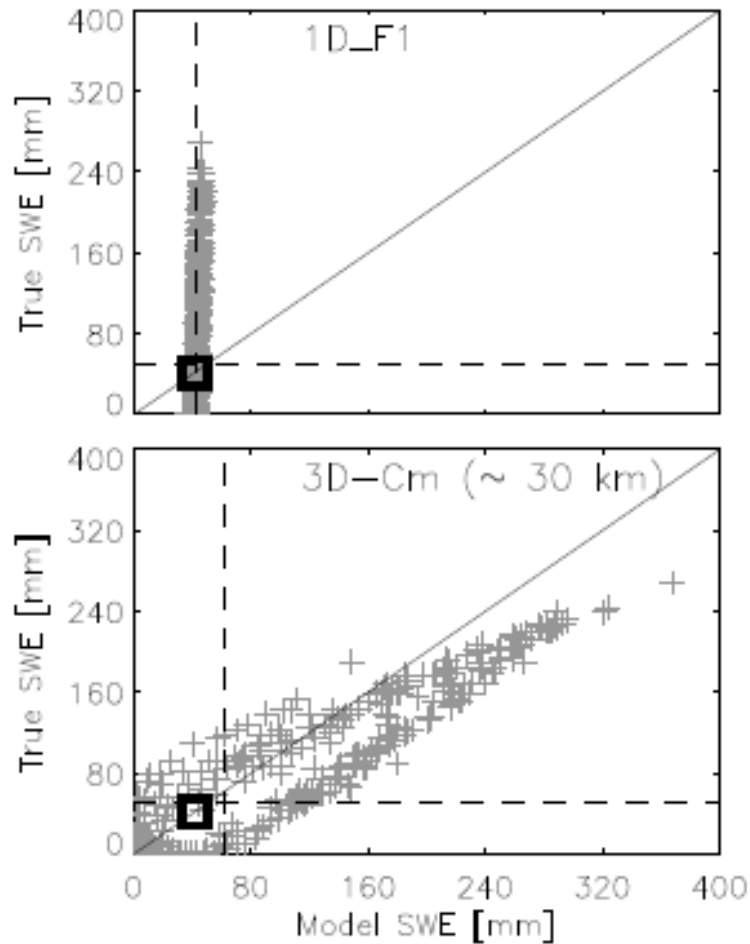
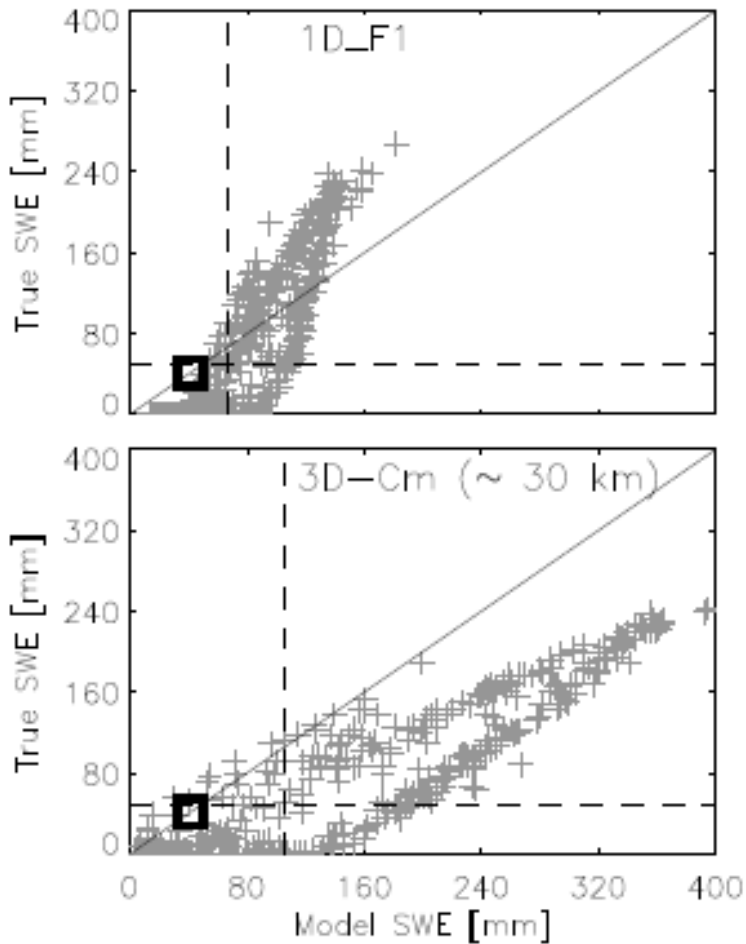


SWE assimilation and downscaling

Forecast



Analysis



Disagg.
obs., 1D

3D, obs.
operator

Obs. operator with 3D update preserves fine-scale structure of model background.



Outline

Land surface observations and modeling

Land data assimilation methods

Examples – NOT a review!

- Soil moisture
- Land surface temperature
- Snow
- Terrestrial water storage

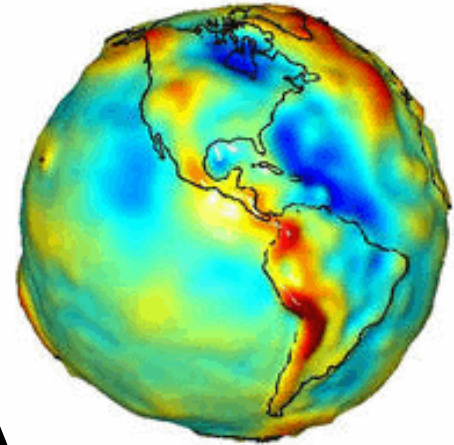
Error modeling and adaptive filtering



GRACE measurements



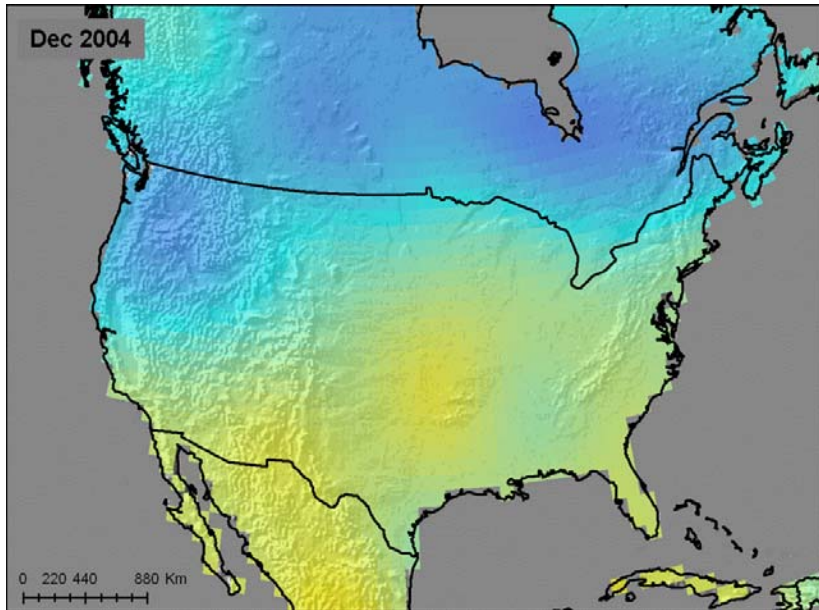
Highly accurate measurement of distance between twin satellites



Gravity anomaly

“Fast” signal (weekly to monthly; after correction for atmospheric pressure)

Terrestrial water storage (TWS) anomaly

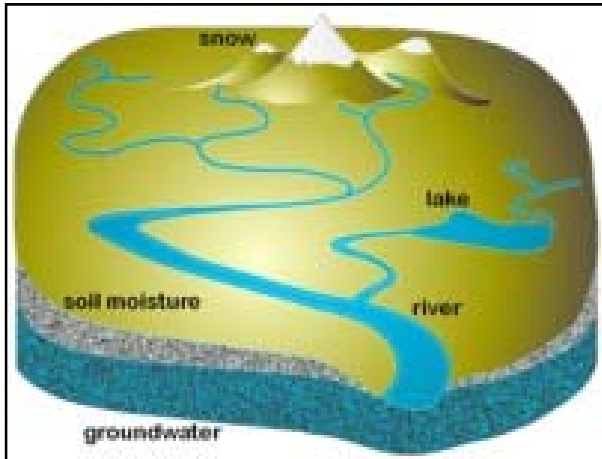


-15.0 15.0
Water Storage Anomaly (cm)



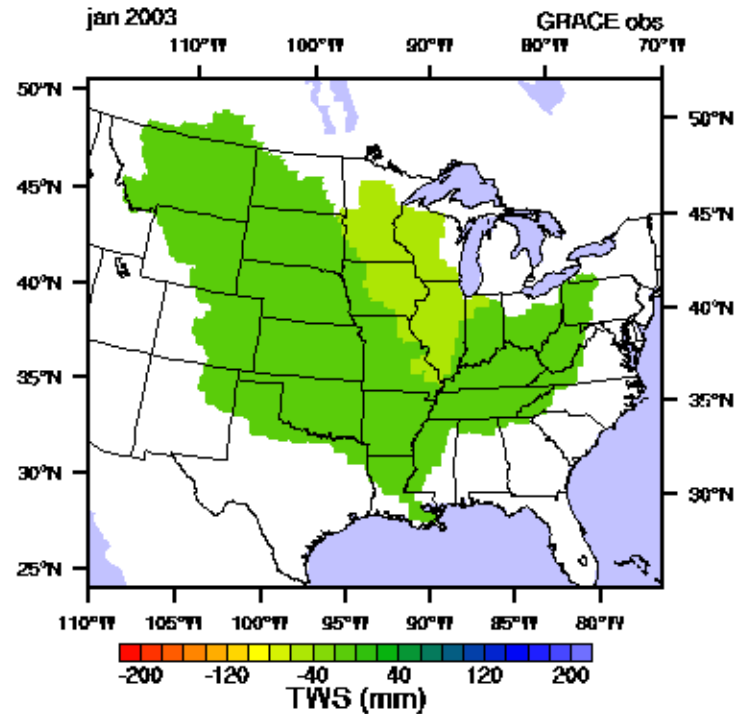
Assimilation of GRACE terrestrial water storage (TWS)

GRACE measures **monthly, basin-scale TWS**
= groundwater + soil moisture + snow + surface water



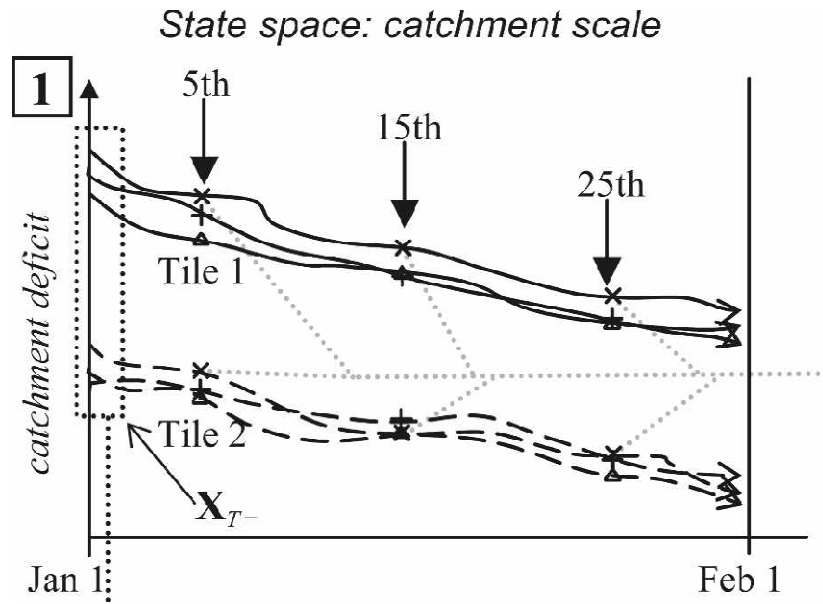
Assimilation should down-scale GRACE observations in space and in time

GRACE TWS anomaly (Jan. 2003 – Jun. 2006 loop)





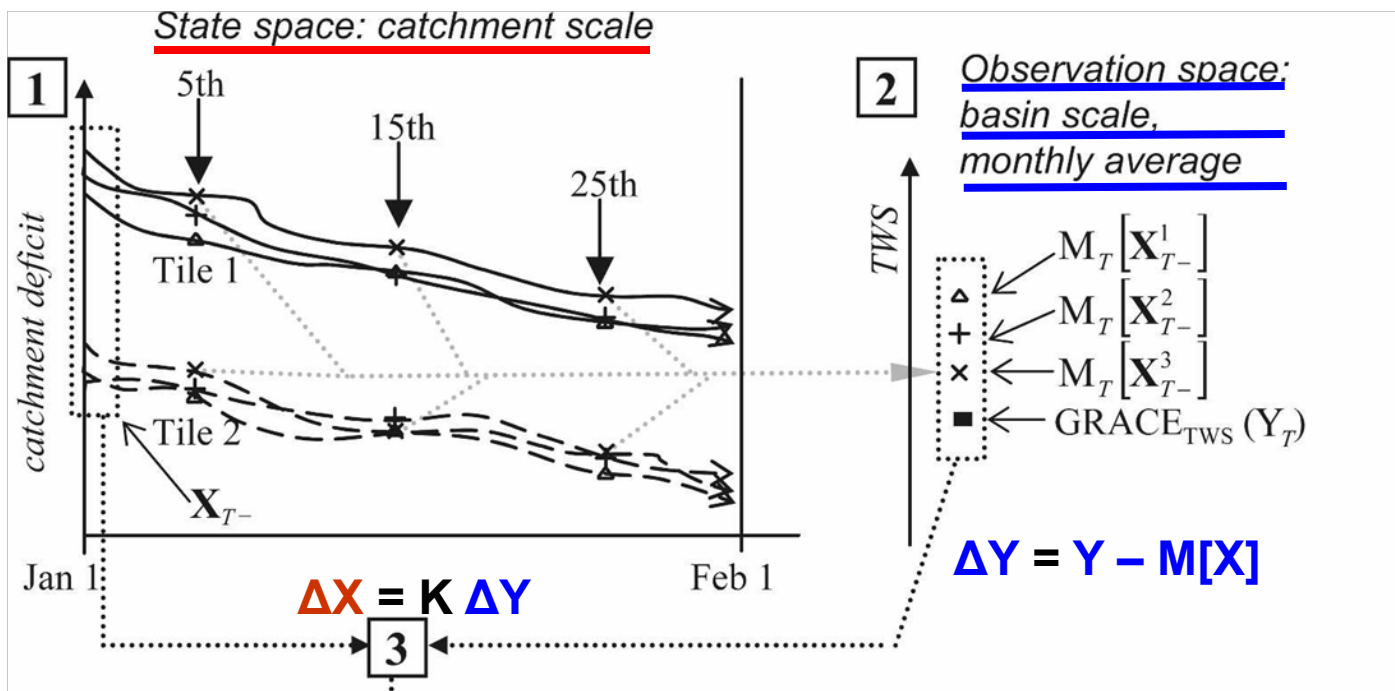
Ensemble Kalman smoother



1.) Run high-resolution land model forecast for one month



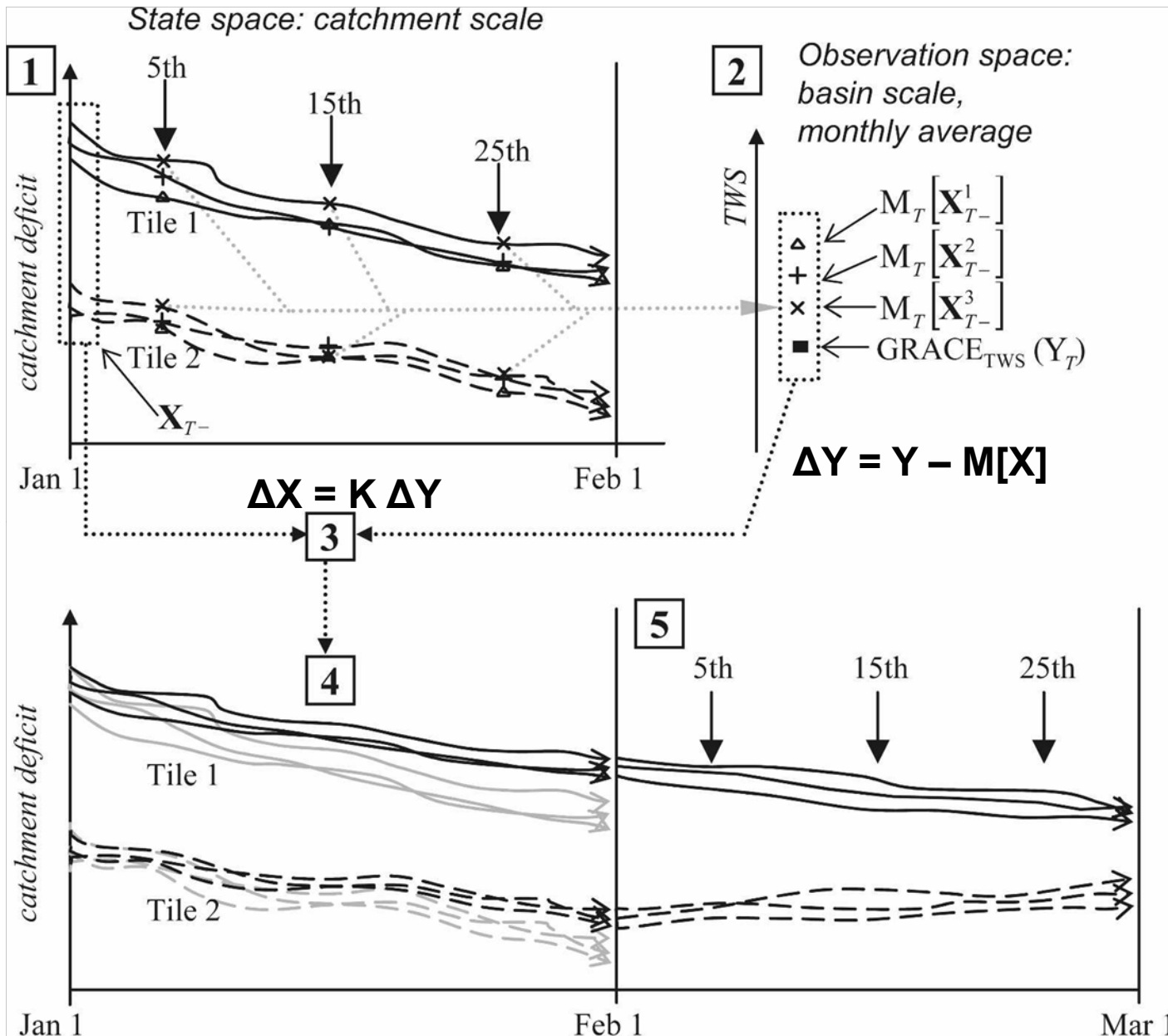
Ensemble Kalman smoother



- 1.) Run high-resolution land model forecast for one month
- 2.) Diagnose large-scale TWS on the 5th, 15th, and 25th, compute innovations (ΔY), Kalman gain (K)
- 3.) Compute increments (ΔX)



Ensemble Kalman smoother

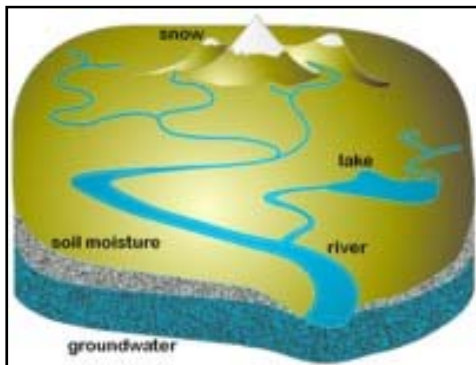


- 1.) Run high-resolution land model forecast for one month
- 2.) Diagnose large-scale TWS on the 5th, 15th, and 25th, compute innovations (ΔY), Kalman gain (K)
- 3.) Compute increments (ΔX)
- 4.) Apply increments *during* second integration
- 5.) Repeat for next month...



Assimilation of GRACE terrestrial water storage (TWS)

GRACE measures
large-scale TWS
= groundwater
+ soil moisture
+ snow
+ surface water



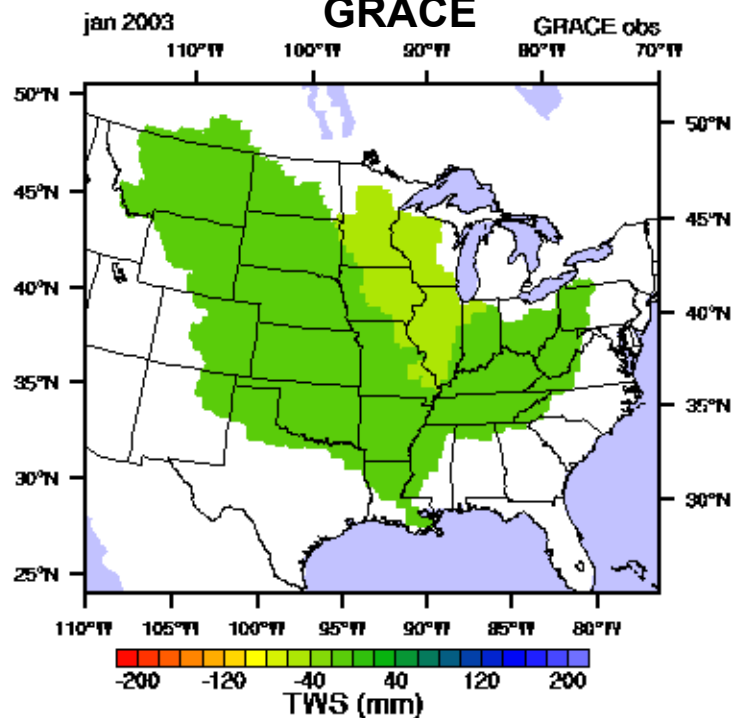
Assimilation yields:

- fine-scale information subject to GRACE basin-scale constraints
- better runoff than model (not shown).

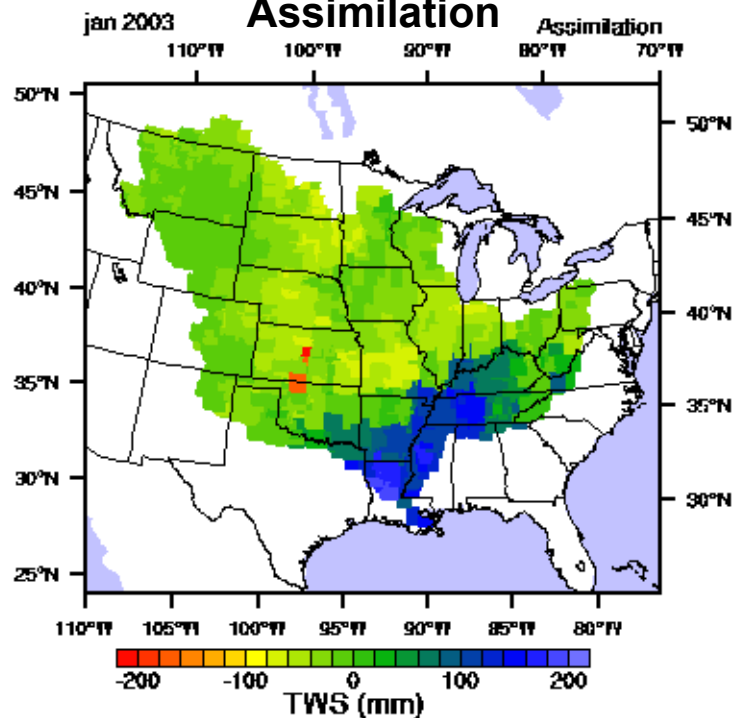


Terrestrial water storage anomaly (Jan. 2003 – Jun. 2006 loop)

GRACE

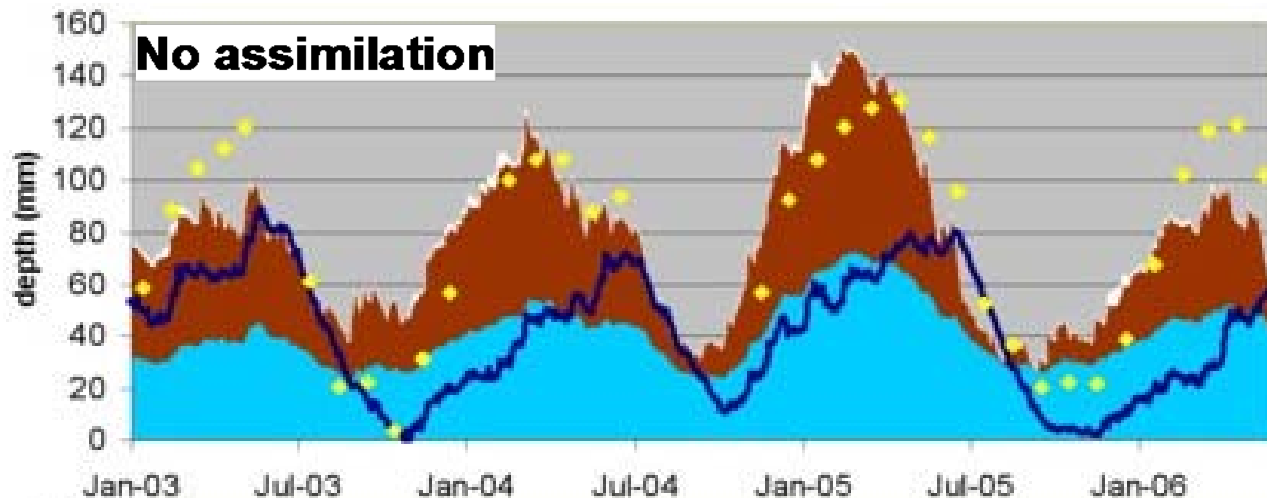


Assimilation



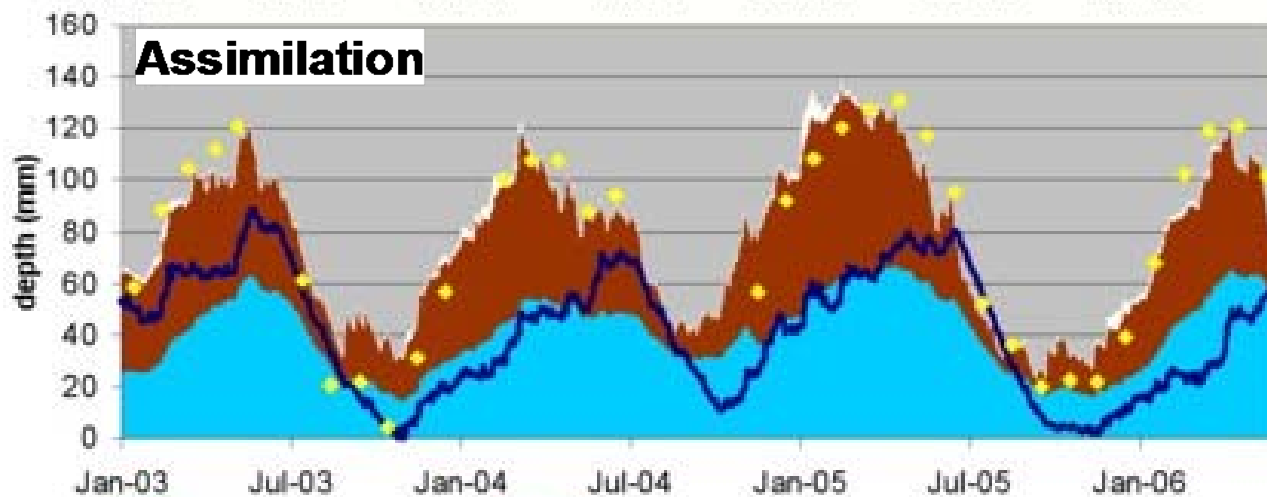


Assimilation of GRACE terrestrial water storage (TWS)

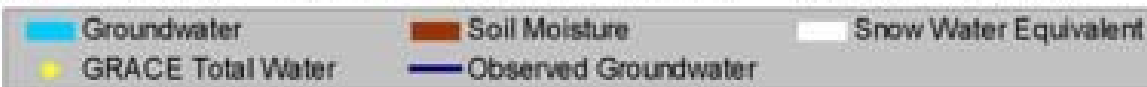


Validation against
observed
groundwater:

RMSE = 23.5 mm
 $R^2 = 0.35$



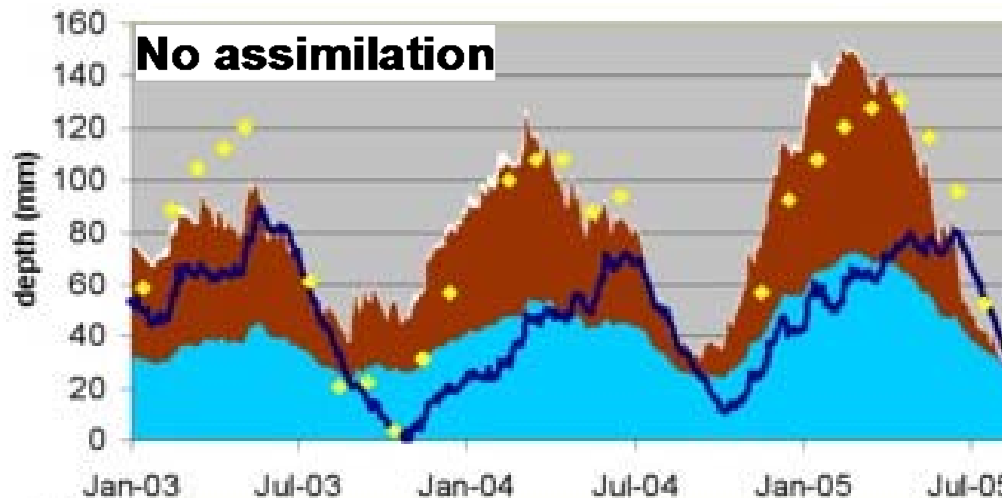
RMSE = 18.5 mm
 $R^2 = 0.49$



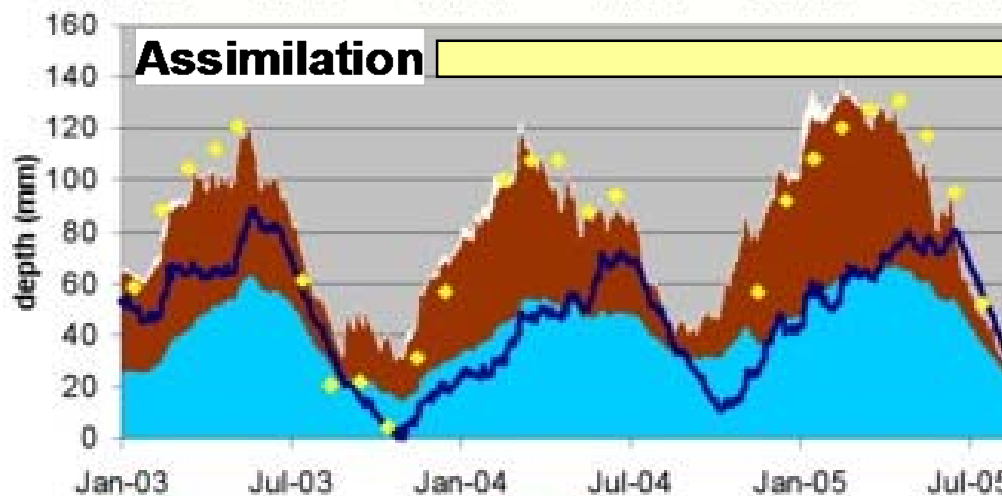
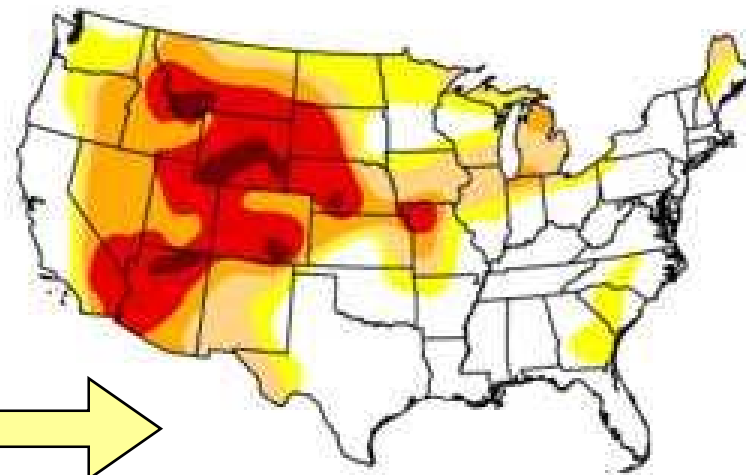
Assimilation disaggregates GRACE data into snow, soil moisture, and groundwater. Assimilation estimates of groundwater better than model estimates.



Assimilation of GRACE terrestrial water storage (TWS)



Application: US Drought Monitor



Intensity:

- D0 Abnormally Dry
- D1 Drought - Moderate
- D2 Drought - Severe
- D3 Drought - Extreme
- D4 Drought - Exceptional

Groundwater Soil Moisture Snow Water Equivalent
 GRACE Total Water Observed Groundwater

Assimilation disaggregates GRACE data into snow, soil moisture, and groundwater.
Assimilation estimates of groundwater better than model estimates.



Outline

Land surface observations and modeling

Land data assimilation methods

Examples – NOT a review!

- Soil moisture
- Land surface temperature
- Snow
- Terrestrial water storage

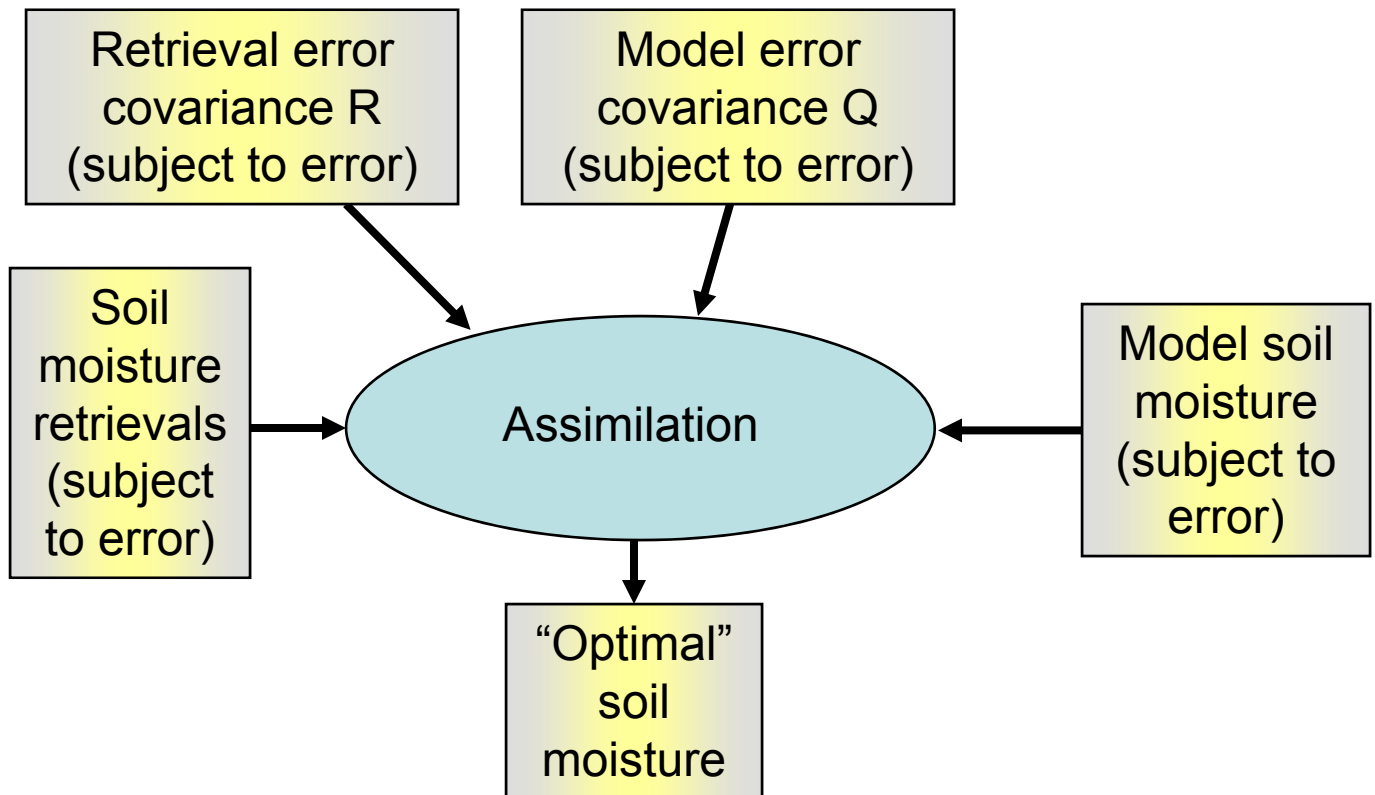
Error modeling and adaptive filtering



Input error parameters Q and R

Weights themselves are subject to error!!!
Wrong weights may lead to poor estimates.

Study sensitivity to error parameters in a synthetic experiment

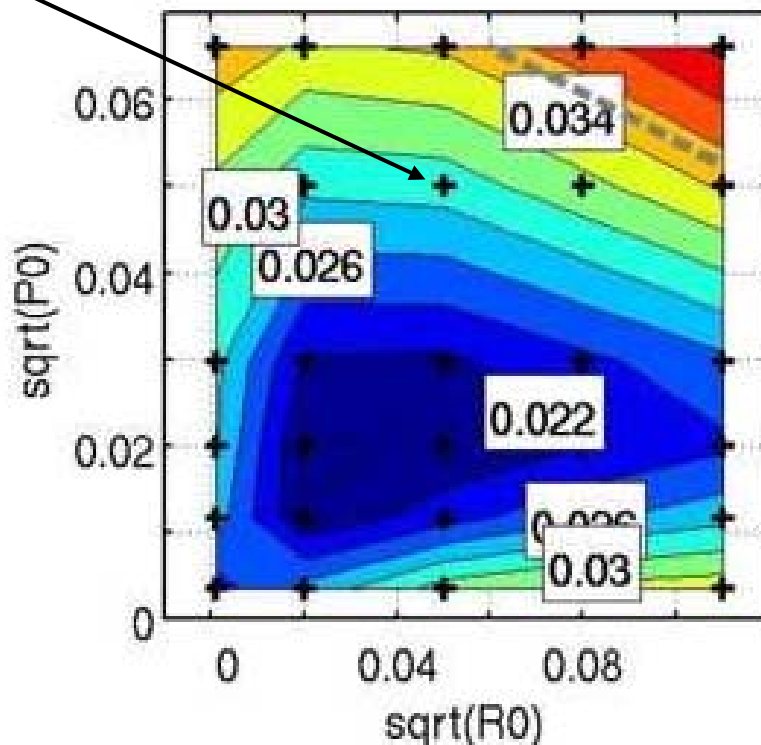




Impact of Q and R on assimilation estimates

RMSE of assimilation estimates v. truth for:

Surface soil moisture m^3/m^3
 $\text{sqrt}(R_true)=0.05, OL=0.035$



Each “+” symbol represents one 19-year assim. experiment over the Red-Arkansas with a unique combination of input model and observation error parameters.

Q = model error (including errors in precip, radiation, and soil moisture tendencies)

P = P(Q) = soil moisture error variance

forecast error std-dev

input obs error std-dev

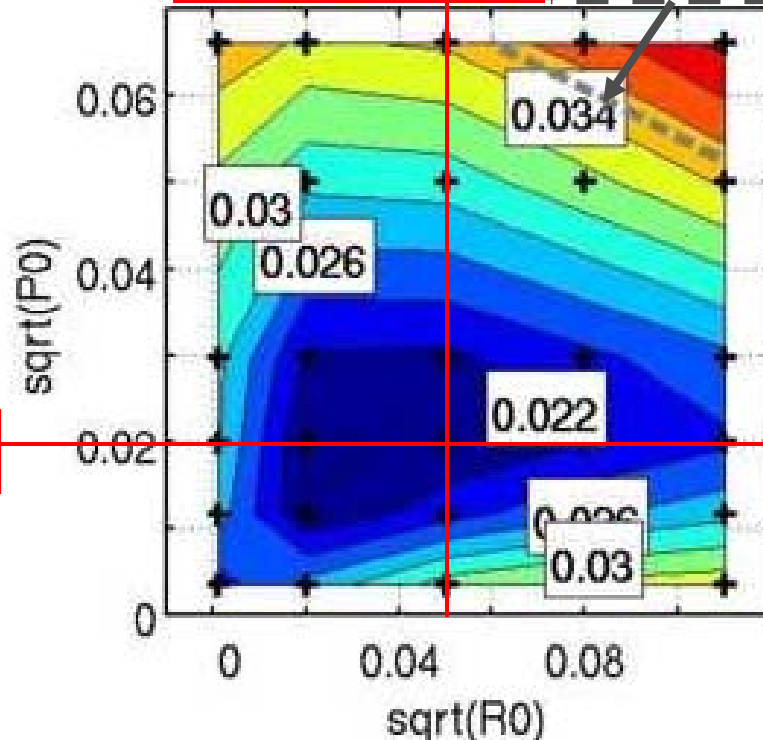


Impact of Q and R on assimilation estimates

RMSE of assimilation estimates v. truth for:

Surface soil moisture m^3/m^3

$\sqrt{R_{\text{true}}}=0.05$, OL=0.035



- “True” input error covariances yield minimum estimation errors.
- Wrong model and obs. error covariance inputs degrade assimilation estimates.
- In most cases, assimilation still better than open loop (OL).



Impact of Q and R on assimilation estimates

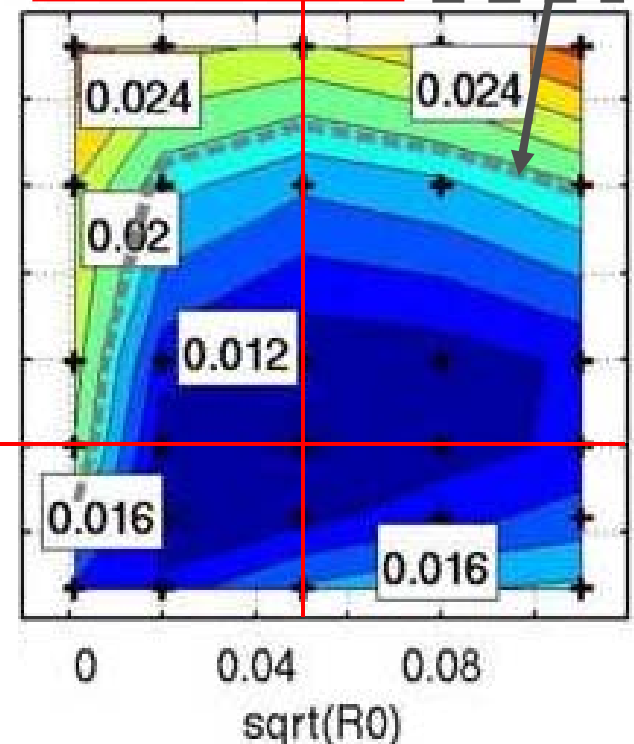
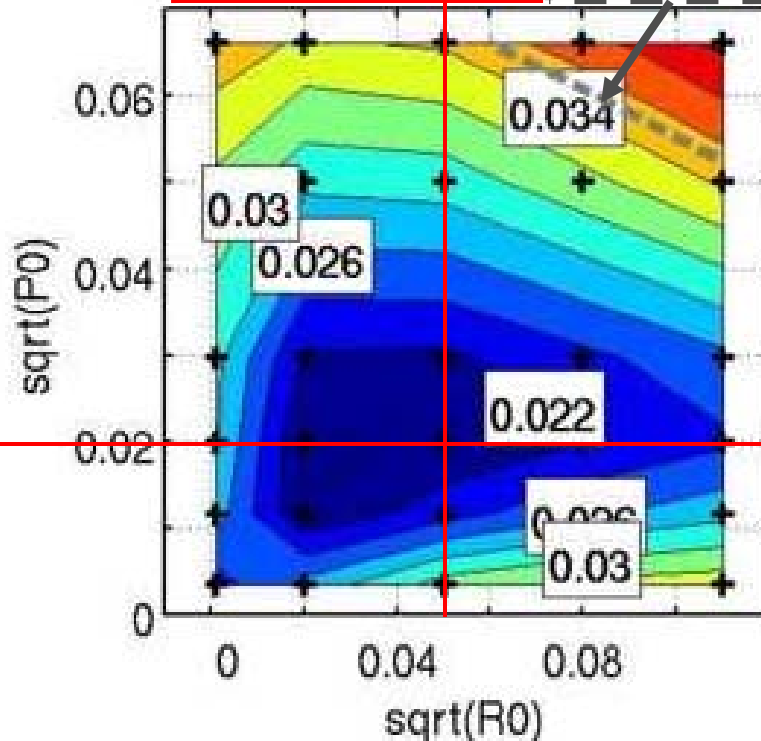
RMSE of assimilation estimates v. truth for:

Surface soil moisture m^3/m^3

Root zone soil moisture m^3/m^3

$\sqrt{R_{\text{true}}}=0.05$, $OL=0.035$

$\sqrt{R_{\text{true}}}=0.05$, $OL=0.020$



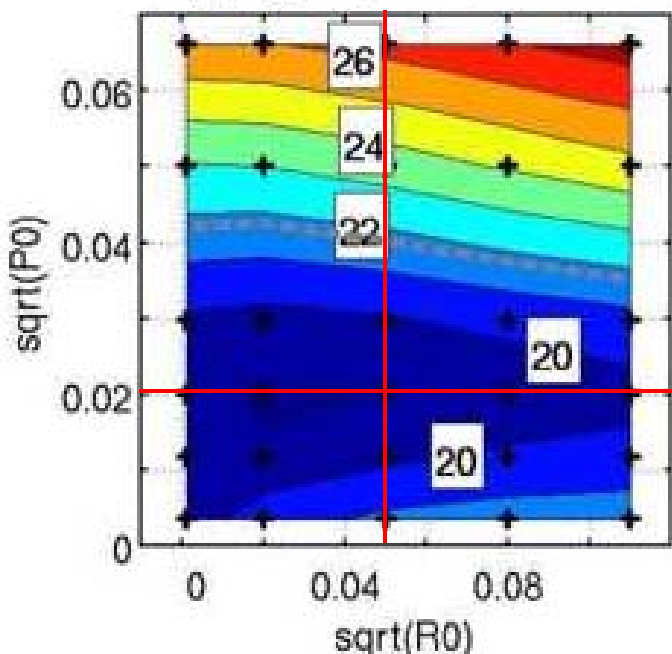
- Root zone more sensitive than surface soil moisture.



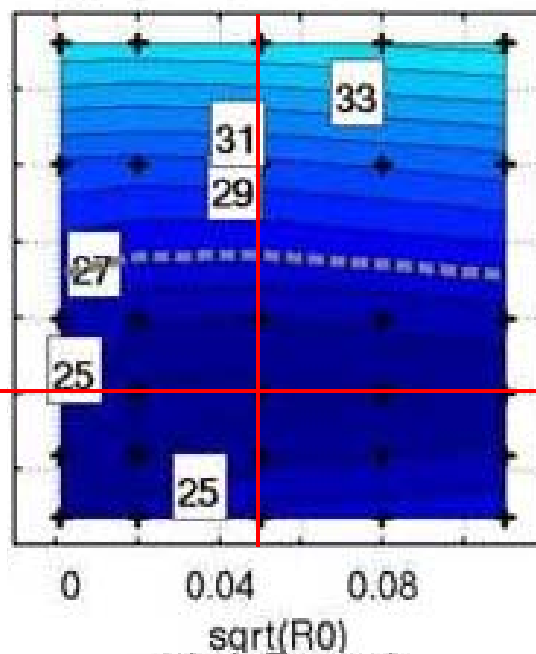
Impact of Q and R on assimilation estimates (fluxes)

RMSE of assimilation estimates v. truth for:

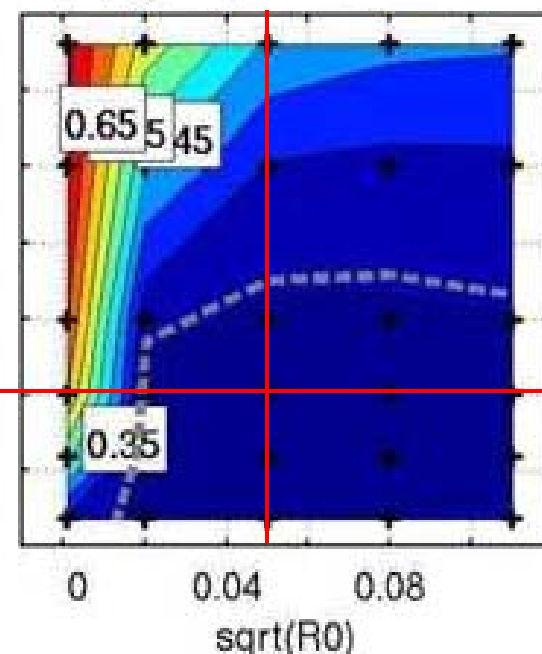
Sensible heat flux W/m^2
 $\text{sqrt}(R_true)=0.05$, $OL=21.749$



Latent heat flux W/m^2
 $\text{sqrt}(R_true)=0.05$, $OL=26.932$



Runoff mm/d
 $\text{sqrt}(R_true)=0.05$, $OL=0.305$



- Fluxes more sensitive to wrong error parameters than soil moisture.
- Sensible/latent heat more sensitive to model error cov than obs error cov (probably related to ensemble propagation).

Diagnostics of filter performance and adaptive filtering

Find true Q, R by enumeration?

- RMSE plots require “truth” (not usually available).
- Too expensive computationally.

Use diagnostics that are available within the assimilation system.

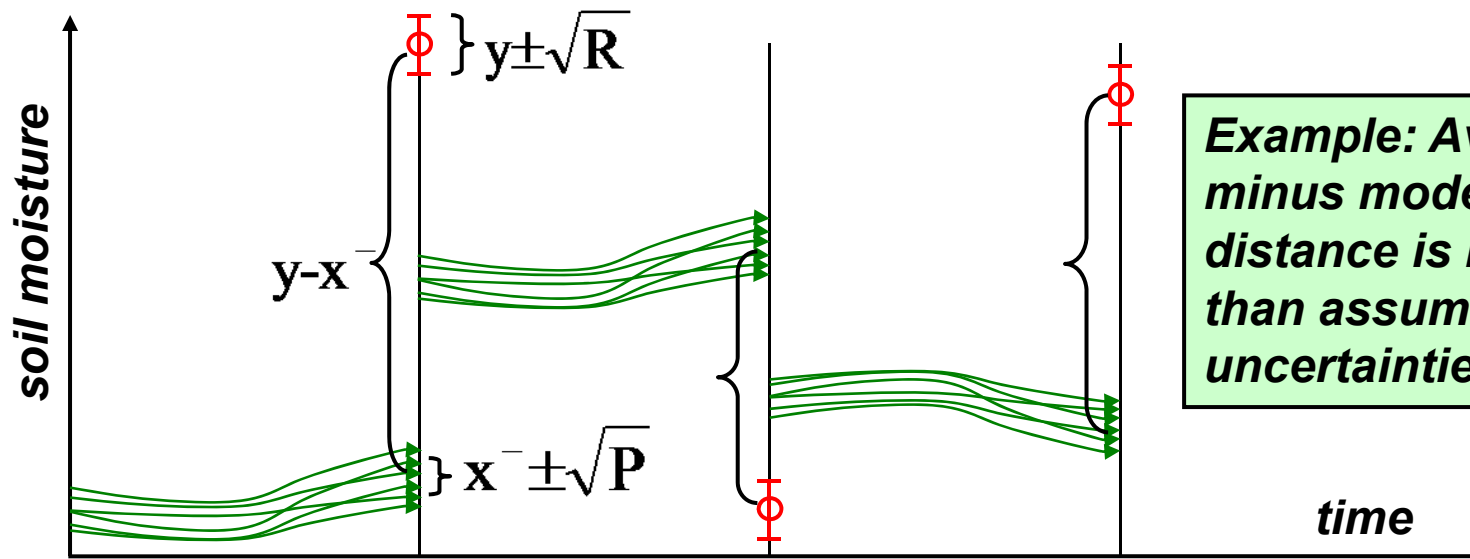
Filter update: $\mathbf{x}^+ = \mathbf{x}^- + \mathbf{K}(\mathbf{y} - \mathbf{x}^-)$
 $\mathbf{K} = \mathbf{P}(\mathbf{P} + \mathbf{R})^{-1} = \text{Kalman gain}$

Diagnostic: $E[(\mathbf{y} - \mathbf{x}^-)(\mathbf{y} - \mathbf{x}^-)^T] = \mathbf{P} + \mathbf{R}$

\mathbf{x}^- = model forecast
 \mathbf{x}^+ = “analysis”
 \mathbf{y} = observation

innovations \equiv obs – model prediction
 (internal diagnostic)

state err cov + obs err cov
 (controlled by inputs)



Example: Average “obs. minus model prediction” distance is much larger than assumed input uncertainties

Diagnostics of filter performance and adaptive filtering

Find true Q, R by enumeration?

- RMSE plots require “truth” (not usually available).
- Too expensive computationally.

Use diagnostics that are available within the assimilation system.

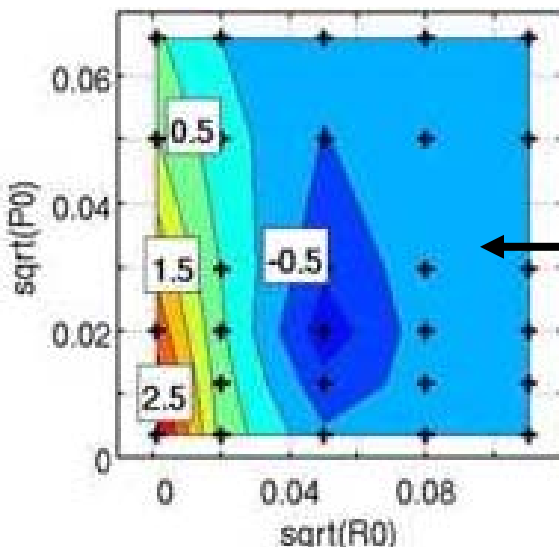
Filter update: $\mathbf{x}^+ = \mathbf{x}^- + \mathbf{K}(\mathbf{y} - \mathbf{x}^-)$
 $\mathbf{K} = \mathbf{P} (\mathbf{P} + \mathbf{R})^{-1} = \text{Kalman gain}$

Diagnostic: $E[(\mathbf{y} - \mathbf{x}^-) (\mathbf{y} - \mathbf{x}^-)^T] = \mathbf{P} + \mathbf{R}$

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**innovations \equiv obs – model prediction
(internal diagnostic)**

**state err cov + obs err cov
(controlled by inputs)**



Contours: \log_{10} of misfit between diagnostic and what it “should” be.

Adaptive filter: Nudge input error parameters (Q, R) during assimilation to minimize misfit.

Diagnostics of filter performance and adaptive filtering

Find true Q, R by enumeration?

- RMSE plots require “truth” (not usually available).
- Too expensive computationally.

Use diagnostics that are available within the assimilation system.

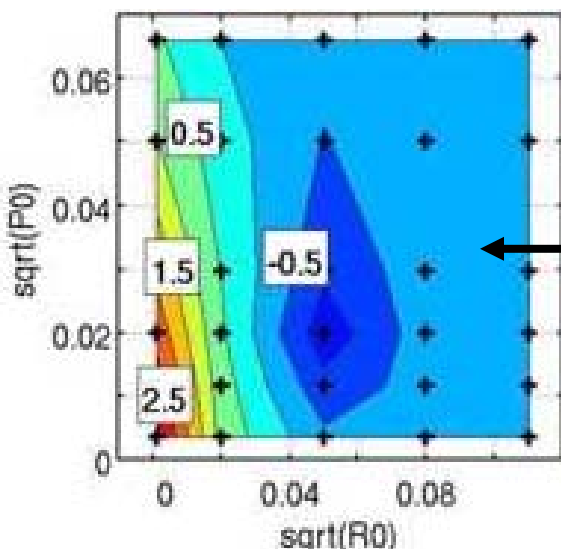
Filter update: $\mathbf{x}^+ = \mathbf{x}^- + \mathbf{K}(\mathbf{y} - \mathbf{x}^-)$
 $\mathbf{K} = \mathbf{P} (\mathbf{P} + \mathbf{R})^{-1} = \text{Kalman gain}$

Diagnostic: $E[(\mathbf{y} - \mathbf{x}^-) (\mathbf{y} - \mathbf{x}^-)^T] = \mathbf{P} + \mathbf{R}$

\mathbf{x}^- = model forecast
 \mathbf{x}^+ = “analysis”
 \mathbf{y} = observation

**innovations \equiv obs – model prediction
 (internal diagnostic)**

**state err cov + obs err cov
 (controlled by inputs)**



Contours: misfit between diagnostic and what it “should” be.

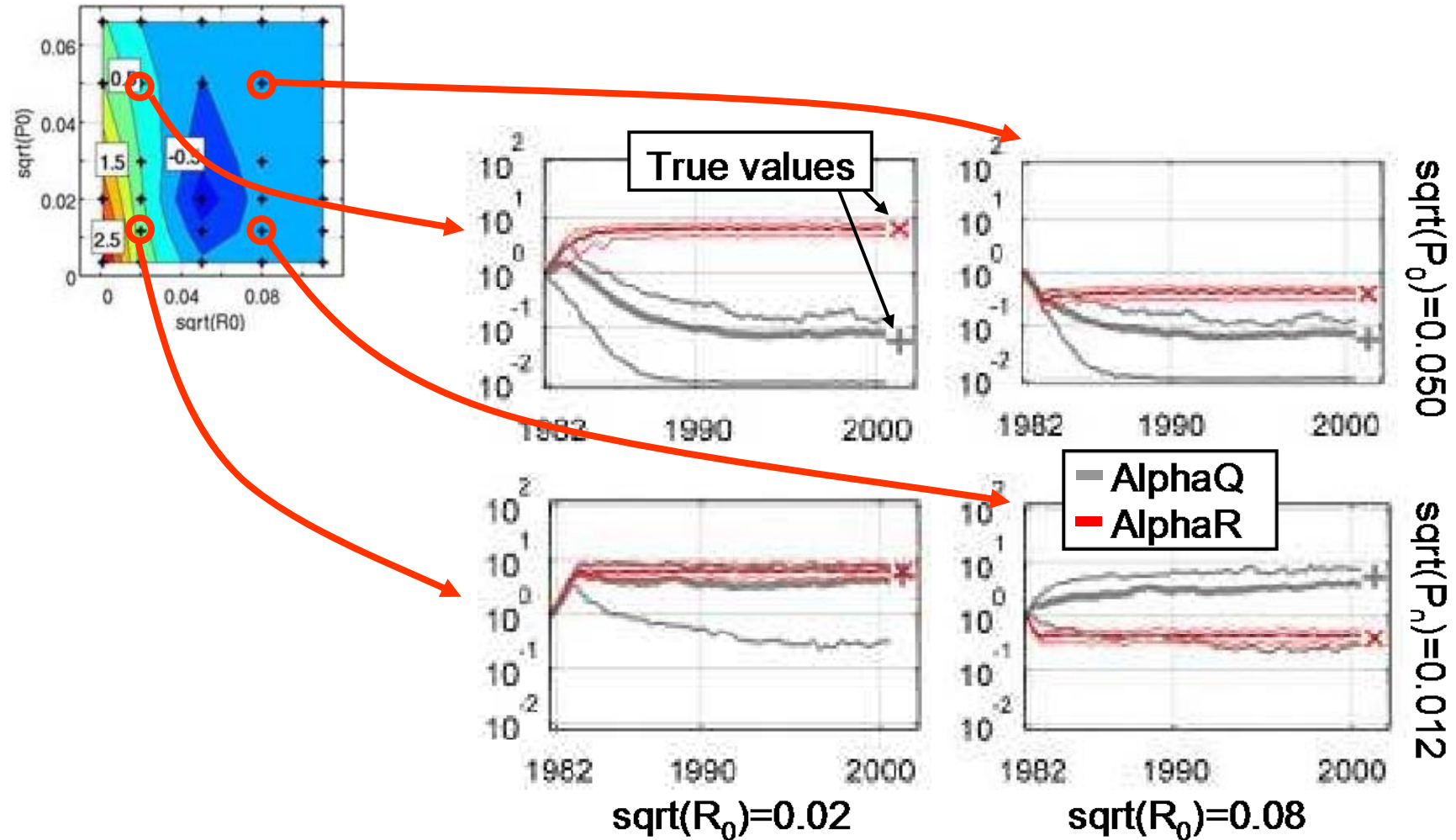
Adaptive filter: Nudge input error parameters (Q, R) during assimilation to minimize misfit.

Diagnostic 1: $E[(\mathbf{y} - \mathbf{x}^+) (\mathbf{y} - \mathbf{x}^-)^T] = \mathbf{R}$

Diagnostic 2: $E[(\mathbf{x}^+ - \mathbf{x}^-) (\mathbf{y} - \mathbf{x}^-)^T] = \mathbf{P}(\mathbf{Q})$



Convergence of adaptive scaling factors



- Adaptive scaling factors generally converge to true values (thick lines).
- Convergence is slow (order of years).
- Spatial variability (thin lines) much greater for α_Q than for α_R .

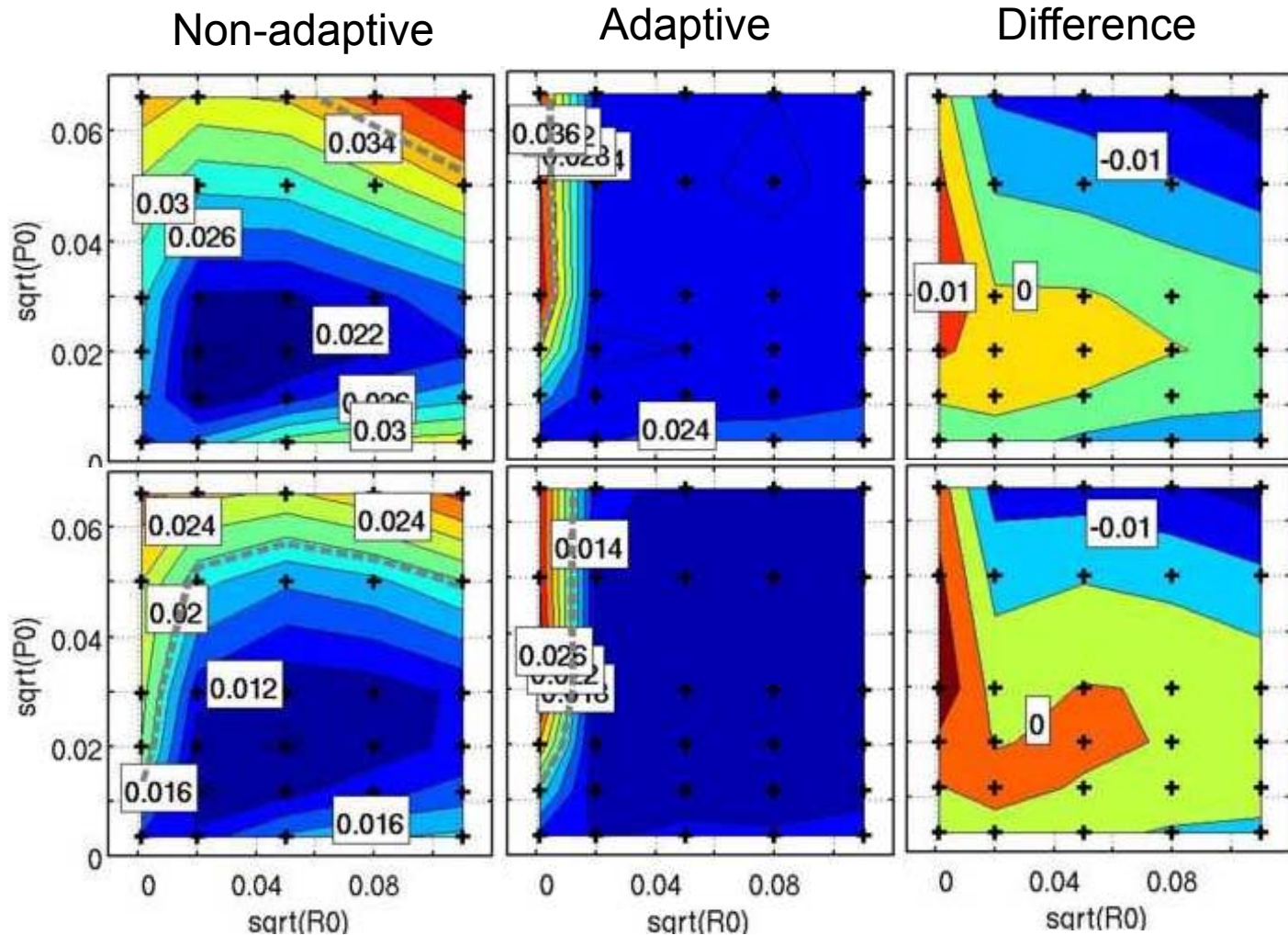


Adaptive v. non-adaptive EnKF (soil moisture)

Surface soil moisture m^3/m^3

Contours: RMSE of assim. estimates v. truth

Root zone soil moisture m^3/m^3

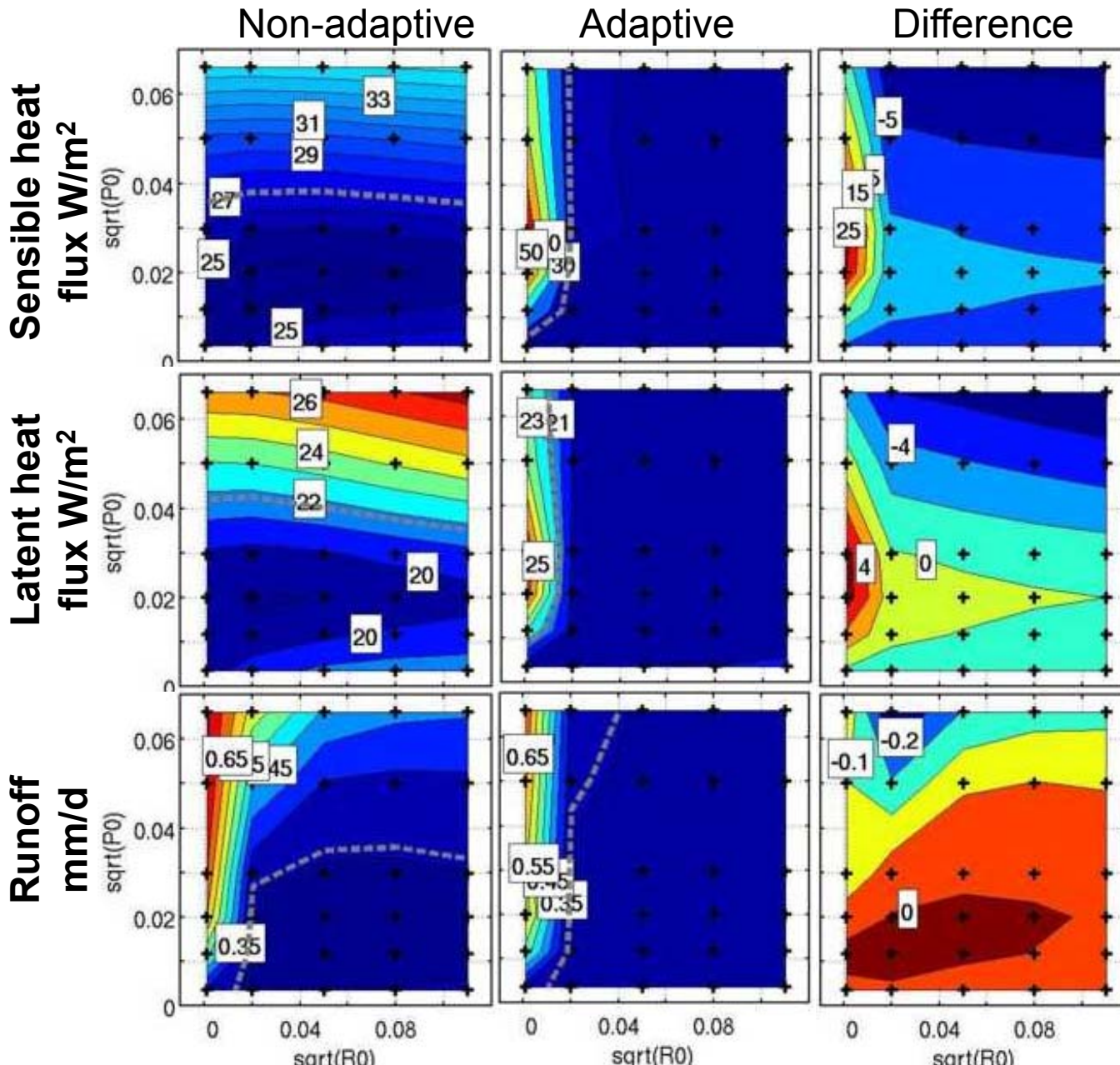


- Adaptive filter: Map experiment onto contour plot based on initial guess of R , $P(Q)$.
- Adaptive filter yields improved assimilation estimates for initially wrong model and observation error inputs (except for $R_0=0$).



Adaptive v. non-adaptive EnKF (fluxes)

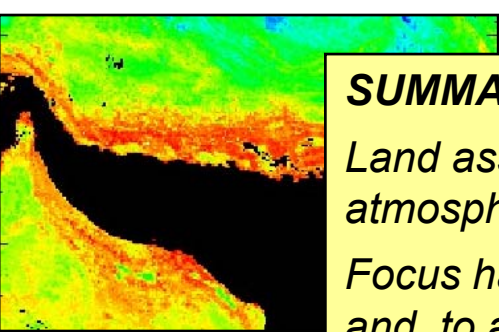
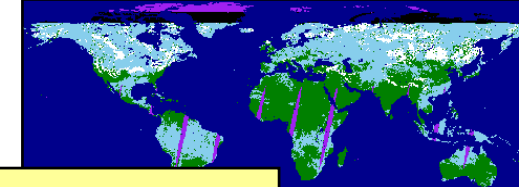
Contours: RMSE of assim. est. v. truth



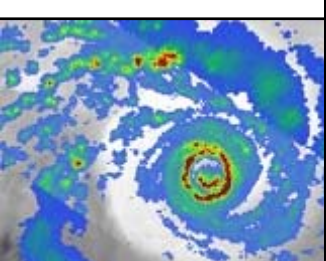
- Adaptive filter generally yields improved flux estimates.
- Degradation when R is severely underestimated.
→ Simply choose large R at the start and let the filter adapt it.



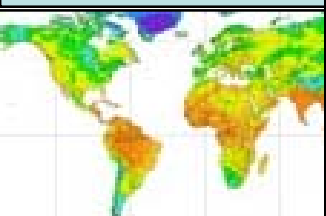
Summary and outlook



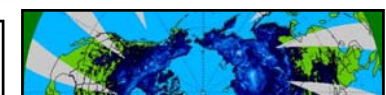
Land surface temperature (MODIS, AVHRR, GPM)



Precipitation (TRMM, GPM)



Radiation (CERES, CLARRA)



SUMMARY

Land assimilation is very **different** from assimilation in the atmosphere and ocean – damped model physics, lack of adjoint.

Focus has been on **univariate, off-line** assimilation of soil moisture and, to a lesser extent, snow, LST, and TWS.

Observations are typically **no more accurate** than model estimates.

Bias between and amongst observational data sets and models require special attention (a priori scaling and/or dynamic estimation).

Assimilation can improve estimates of land surface states, e.g. **root-zone soil moisture** (not directly observed).

Down-scaling can be accomplished within the assimilation system.

Adaptive filtering may help with estimation of model and observation error parameters.

OUTLOOK

Multi-variate assimilation of soil moisture, LST, snow cover, and snow water equivalent.

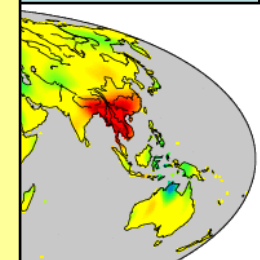
Integrate land and atmospheric data assimilation and investigate feedbacks in **coupled** land-atmosphere analysis system.

Prepare for **new satellite sensors** (SMOS, SMAP & other Decadal Survey) and **new models** (dynamic vegetation, crop-growth models)

Water fraction (MODIS, MIS)



Surface elevation (ICESat, WOT)



Terrestrial biogeochemistry (GRACE)



Carbon (MODIS, DESDynI, GPP, SPIRI, LIST, ASCENDS)



THANK YOU FOR YOUR ATTENTION!